

ELEVATOR EC CONTROLS
SIMPLE. SOLID. SUPPORTABLE.

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16-18550

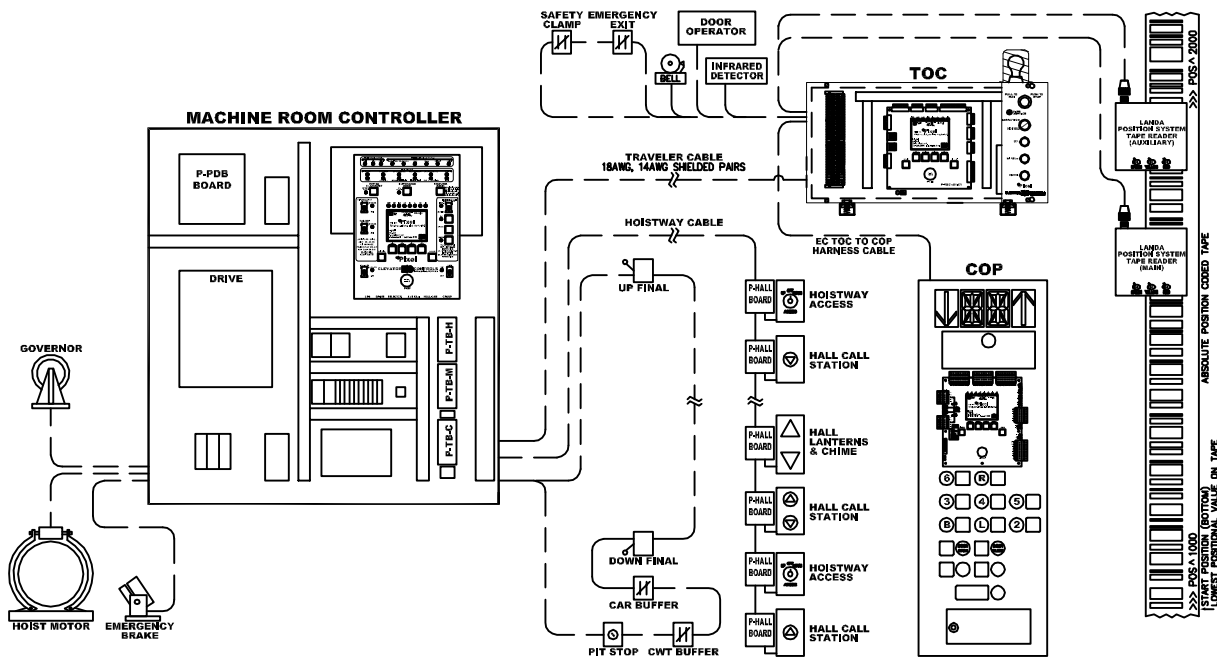
SIMPLEX

PIXEL AC VECTOR-MRL-S

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TYPICAL Pixel CONTROLLER INTERCONNECTION OVERVIEW



PIXEL CONSTRUCTION MODE OPERATION

CONSTRUCTION MODE OPERATION ALLOWS QUALIFIED ELEVATOR PERSONAL TO RUN THE CAR ON CARTOP & MACHINE ROOM WITH MINIMAL FIELD WIRING. THE TOP OF CAR BOX (TOC), LANDA POSITION SYSTEM & P-COP BOARD ARE NOT REQUIRED TO RUN THE CAR ON CONSTRUCTION MODE. THE MAXIMUM SPEED IS 50FPM OR PROGRAMMED INSPECTION SPEED, WHICHEVER IS LESS.

1 COMPLETE POWER, HOIST MOTOR AND BRAKE CONNECTIONS (REFER TO PAGE QR4 FOR HOISTWAY WIRING DIAGRAMS)

- ☐ A. VERIFY DISCONNECT POWER IS WITHIN 10% OF SPECIFIED VOLTAGE ON PAGE QR4 (OR PAGE 1)
- ☐ B. WIRE THE DISCONNECT TO CONTROLLER PER PAGE QR4 (OR PAGE 1)
- ☐ C. VERIFY THE HOIST MOTOR AND BRAKE DATA PLATES MATCH THE JOB PRINTS (PAGES 1 & 2)
- ☐ D. WIRE THE HOIST MOTOR AND MAIN BRAKE TO CONTROLLER PER PAGE QR4 (OR PAGES 1 & 2)
- ☐ E. WIRE THE VELOCITY ENCODER TO THE DRIVE ENCODER CARD PER PAGE QR4 (OR PAGE 1)
- ☐ F. IF AN INDEPENDENT MACHINE BRAKE IS USED FOR THE EMERGENCY BRAKE WIRE TO CONTROLLER PER PAGE QR4 (OR PAGE 2)

2 PLACE PIXEL CONTROL SYSTEM ON CONSTRUCTION MODE OPERATION

- ☐ IF THE PIXEL P-MP BOARD DISPLAYS "CONSTRUCTION" AT THE TOP OF THE LCD SKIP TO STEP 3
- ☐ A. PIXEL SWITCH PRESETTING: MACHINE ROOM INSPECTION=INSP POSITION, TEST=TEST POSITION & CAPTURE=CAPTURE POSITION
- ☐ B. FROM THE HOME SCREEN, SELECT "INSTALL" MENU USING THE TOUCH & GO KNOB
- ☐ C. ONCE IN THE INSTALLATION MENU SELECT "CONSTRUCTION MODE" USING THE TOUCH & GO KNOB
- ☐ D. AT THE CONSTRUCTION MODE MENU PRESS THE "ENABLE" SOFT KEY. IF CONSTRUCTION MODE IS "ACTIVE" SKIP TO STEP 3

3 INSTALL REQUIRED INSPECTION AND SAFETY DEVICES (REFER TO DIAGRAM TO THE RIGHT)

- ☐ A. GOVERNOR OVERSPEED SWITCH (TERMINALS GOV & 4A)
- ☐ B. CARTOP RUN BOX STOP SWITCH (TERMINALS SAFC & 4A)
- ☐ C. CARTOP RUN BOX INSPECTION SWITCH (TERMINALS ICT & 4A)
- ☐ D. CARTOP RUN BOX INSPECTION ENABLE, UP & DOWN BUTTONS (TERMINALS ICTE, ICTU, ICTD & 4A)

4 INSTALL REQUIRED CONSTRUCTION MODE TEMPORARY JUMPERS, IF DEVICES ARE NOT AVAILABLE AT THIS TIME

- ☐ A. HOISTWAY SAFETY STRING (TERMINALS SAFH TO SAFC)
- ☐ B. TOP DOOR LOCK (TERMINALS DLAT TO 4A)
- ☐ C. FRONT INTERMEDIATE DOOR LOCKS (TERMINALS DLSF TO 4A)
- ☐ D. BOTTOM DOOR LOCK (TERMINALS DLAB TO 4A)
- ☐ E. FRONT CAR GATE (TERMINALS CGF TO 4A)
- ☐ F. IF REAR DOORS ARE APPLICABLE, REAR INTERMEDIATE DOOR LOCKS (TERMINALS DLSR TO 4A)
- ☐ G. IF REAR DOORS ARE APPLICABLE, REAR CAR GATE (TERMINALS CGR TO 4A)
- ☐ H. HOISTWAY ACCESS INSPECTION SWITCH (TERMINALS IA TO 4A)
- ☐ I. IN-CAR INSPECTION ENABLE (TERMINALS IIC TO 4A)

NOTE: FOR CARTOP INSPECTION OPERATION ONLY, PLACE THE HOISTWAY AND CAR DOOR LOCK SWITCHES IN THE "BYPASS" POSITION AND SKIP THE INSTALLATION OF THE TEMPORARY DOOR LOCK JUMPERS (STEP 4: B-G). MACHINE ROOM INSPECTION WILL NOT OPERATE WITH HOISTWAY AND/OR CAR DOOR BYPASS SWITCHES IN THE BYPASS POSITION

5 DRIVE PARAMETER VERIFICATION AND SETUP

- ☐ A. VERIFY DRIVE PARAMETERS ON PAGE QR7 MATCH THE ELEVATOR INSTALLATION REQUIREMENTS
- ☐ B. MOTOR AUTO-TUNE (REFER TO PAGE QR7)
- ☐ C. VERIFY PROPER DIRECTIONAL MOVEMENT ON INSPECTION OPERATION (REFER TO PAGE QR7)
- ☐ D. VERIFY RUNNING SPEED VS. COMMANDED SPEED WITH A HANDHELD TACHOMETER
ADJUST THE SPEED AS REQUIRED BY MANIPULATING PARAMETERS (L1000A DRIVE):
E1-04 AND E1-06 SHOULD BE ADJUSTED TO EQUAL VALUES
E1-04 (MAX. OUTPUT FREQUENCY) – LOWER VALUES WILL DECREASE SPEED AND HIGHER VALUES WILL INCREASE SPEED
E1-06 (BASE FREQUENCY) – LOWER VALUES WILL DECREASE SPEED AND HIGHER VALUES WILL INCREASE SPEED

CAUTION: ONCE THE TOC BOX, LANDA POSITION SYSTEM & P-COP BOARD HAVE BEEN INSTALLED AND THE CAR IS READY TO RUN ON AUTOMATIC OPERATION. VERIFY ALL CONSTRUCTION MODE TEMPORARY JUMPERS HAVE BEEN REMOVED AND THE REQUIRED SAFETY DEVICES HAVE BEEN INSTALLED, BEFORE DISABLING CONSTRUCTION MODE.

PIXEL AUTOMATIC OPERATION

6 AUTOMATIC OPERATION REQUIRES THE INSTALLATION OF:

- ☐ HOISTWAY SAFETY DEVICES (PIT STOP SWITCH, COUNTERWEIGHT BUFFER, CAR BUFFER, UP & DOWN FINAL LIMITS...ETC)
- ☐ TOC BOX (CARTOP INSPECTION STATION, EMERGENCY EXIT, SAFETY CLAMP, LANDA POSITION SYSTEM, DOOR OPERATOR, INFRARED DETECTOR...ETC)
- ☐ DOOR LOCKS (CAR GATE(S), HOISTWAY DOOR LOCKS)
- ☐ EMERGENCY BRAKE (ROPE GRIPPER OR INDEPENDENT MACHINE BRAKE...ETC)
- ☐ CAR OPERATING PANEL (HOISTWAY ACCESS, EMERGENCY STOP, CAR CALLS, DOOR BUTTONS, INDEPENDENT SERVICE...ETC)
- ☐ FIRE ALARM INITIATING DEVICES (FIRE PHASE 1 RECALL SWITCH, FIRE SENSORS...ETC)
- ☐ IF APPLICABLE EARTHQUAKE DEVICES (SEISMIC SWITCH, RING & STRING...ETC)

7 PIXEL HOISTWAY POSITION SETUP OVERVIEW (REFER TO PIXEL MANUAL FOR DETAILS):

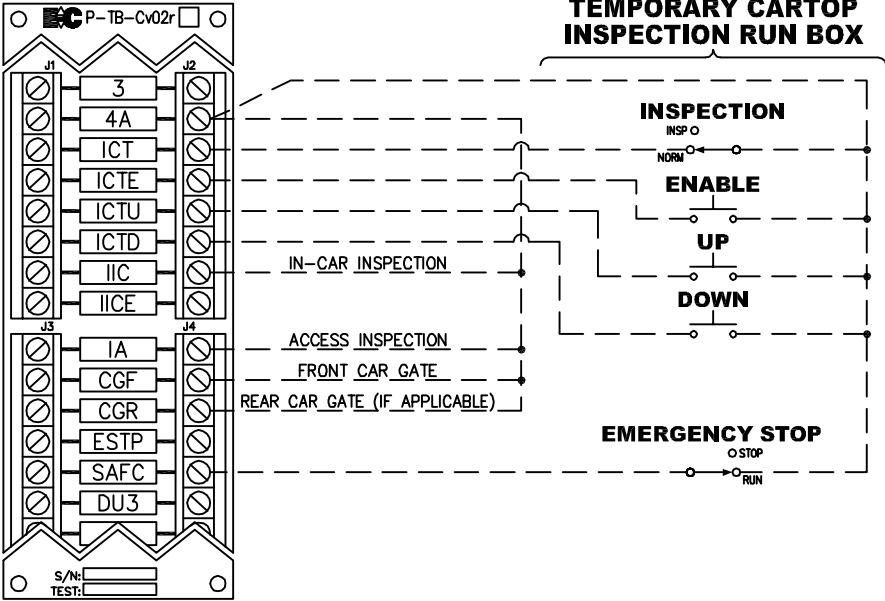
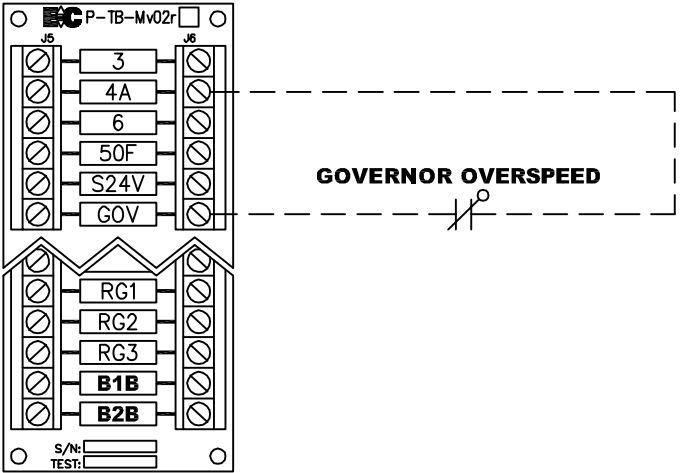
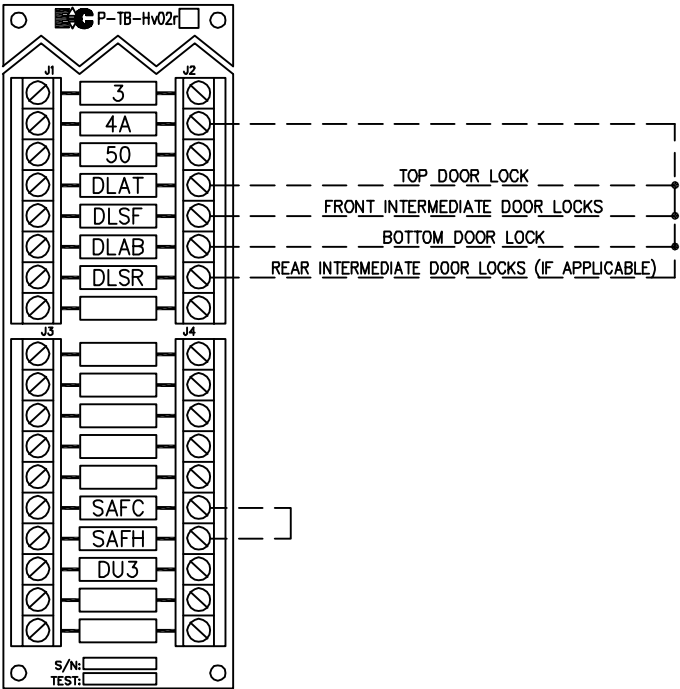
- ☐ A. TAPE READER OFFSET: INSTALL>LEARN FUNCTIONS>VIRTUAL LIMITS>TAPE READER OFFSET, THEN LEARN>SAVE
- ☐ B. FLOOR LANDING DOOR ZONES: INSTALL>LEARN FUNCTIONS>FLOOR SETUP>LANDING NUMBER, THEN DOOR ZONE POSTION>LEARN>SAVE
NOTE: ALWAYS LEARN THE BOTTOM LANDING DOOR ZONE FIRST. THIS NORMALIZES THE HOISTWAY POSITION AND THE BOTTOM LANDING WILL BE SET TO 1.2 FEET. THE VIRTUAL DOWN NORMAL LIMIT WILL BE AUTOMATICALLY SET TO 1.0 FEET.
- ☐ C. BOTTOM (BAL) AND TOP (TAL) HOISTWAY ACCESS LIMIT ZONES: INSTALL>LEARN FUNCTIONS>VIRTUAL LIMITS>BAL & TAL, THEN LEARN>SAVE

8 DISABLE CONSTRUCTION MODE OPERATION

- ☐ A. PIXEL SWITCH PRESETTING: MACHINE ROOM INSPECTION=INSP POSITION, TEST=TEST POSITION & CAPTURE=CAPTURE POSITION
- ☐ B. FROM THE HOME SCREEN, SELECT "INSTALL" MENU USING THE TOUCH & GO KNOB
- ☐ C. ONCE IN THE INSTALLATION MENU SELECT "CONSTRUCTION MODE" USING THE TOUCH & GO KNOB
- ☐ D. AT THE CONSTRUCTION MODE MENU PRESS THE "DISABLE" SOFT KEY, THE CONSTRUCTION MODE MENU WILL NOW DISPLAY "DISABLED"

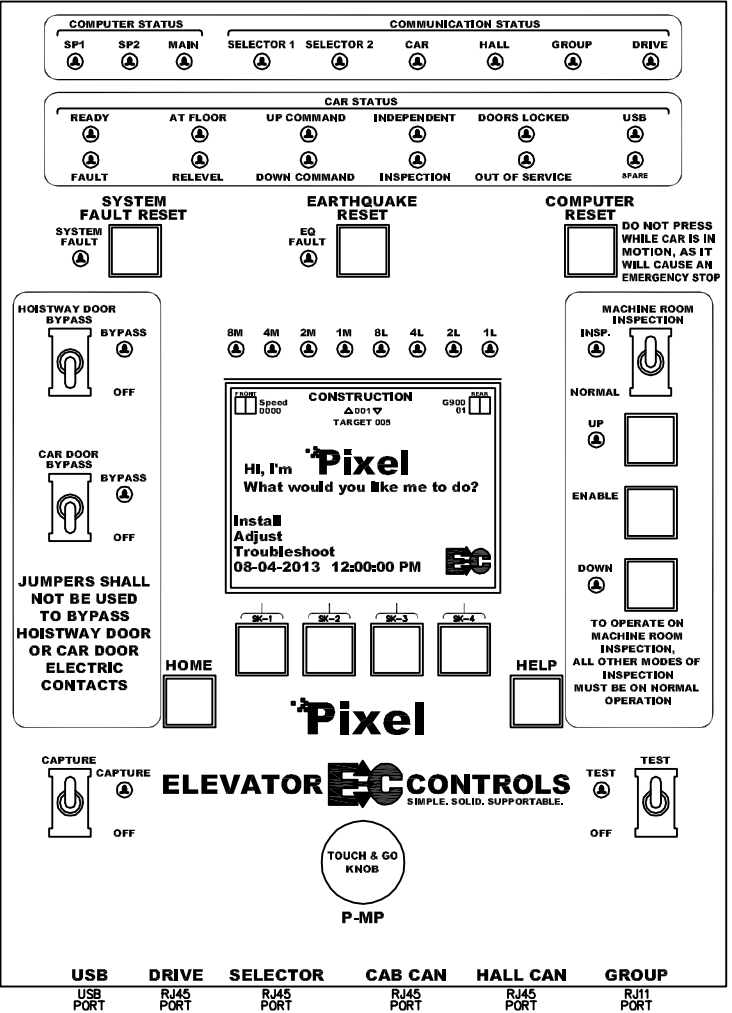
9 PIXEL HOISTWAY TERMINAL SLOWDOWN SETUP (REFER TO PIXEL MANUAL FOR DETAILS):

- ☐ A. TURN OFF MACHINE ROOM INSPECTION & PLACE THE CAR ON TEST MODE. CLEAR ANY FAULTS THAT ARE DISPLAYED.
- ☐ B. REGISTER CAR CALLS TO INTERMEDIATE FLOORS USING THE AUTO CALL SIMULATION SCREEN: TROUBLESHOOT>AUTO CALL SIMULATION>RUN TO FLOOR 00.. DO NOT REGISTER CALLS TO THE TERMINAL LANDINGS UNTIL ETS IS LEARNED.
- ☐ C. BOTTOM & TOP EMERGENCY TERMINAL SLOWDOWN LIMITS: INSTALL>LEARN FUNCTIONS>ETS LEARN>FOLLOW ON SCREEN INSTRUCTIONS, THEN SAVE

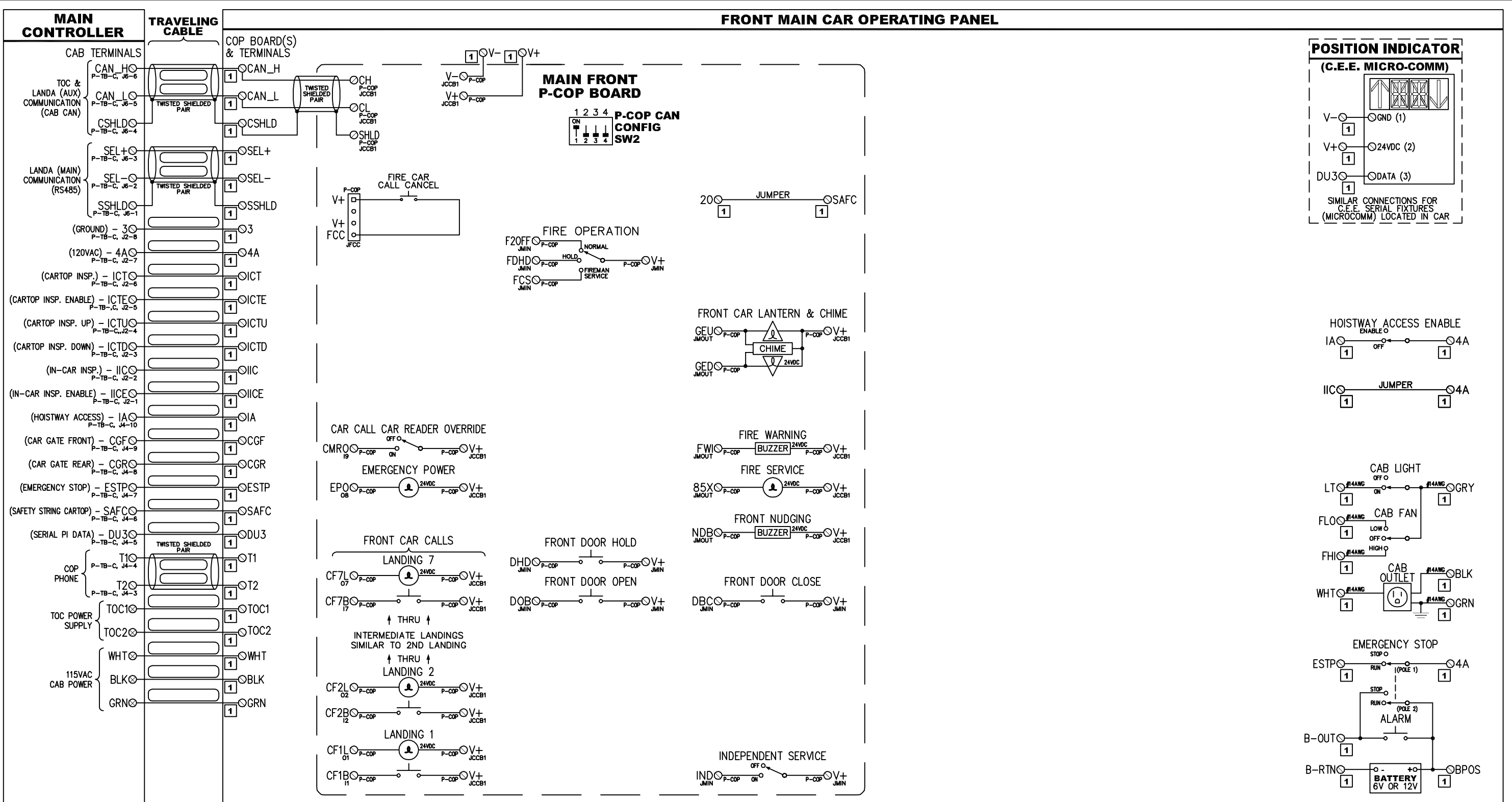


P-MP BOARD SWITCH GEAR NOTES:

- MACHINE ROOM INSPECTION DIRECTIONAL CONTROL REQUIRES UP OR DOWN AND THE ENABLE BUTTON TO BE PUSHED SIMULTANEOUSLY
- CAPTURE SWITCH: DISABLES HALL CALL OPERATION TO COMMANDEER FOR FOR TEST MODE
- TEST SWITCH: DISABLES DOOR & HALL CALL OPERATION FOR TESTING
- HOISTWAY DOOR BYPASS SWITCH: BYPASSES HOISTWAY DOOR SAFETY CIRCUIT ONLY OPERATIONAL ON CARTOP & IN-CAR INSPECTION MODES
- CAR DOOR BYPASS SWITCH: BYPASSES CAR DOOR SAFETY CIRCUIT ONLY OPERATIONAL ON CARTOP & IN-CAR INSPECTION MODES



PIXEL QUICK START UP INSTRUCTIONS			
JOB NAME: 438 W. 51ST ST SE1			
CUSTOMER: G-TECH ASSOCIATES, LLC			
ENGINEERED BY: Jason Kirlis	DATE: 10/27/16	REVISION DATE:	
		CONTROLLER MODEL: PIXEL AC VECTOR-MRL-S	
6150 WAREHOUSE WAY SACRAMENTO, CA 95828 USA PHONE: (800)829-8106 FAX: (916)428-1728 www.elevatorcontrols.com		JOB NUMBER: 16-18550	
M_PIXEL-QR1.dwg	04/30/15	CONTROLLER ID:	PAGE NUMBER: SIMPLEX QR1
FILE: J18550_QR1.dwg			



1 TERMINAL PROVIDED BY COP MANUFACTURER OR CUSTOMER

TOC BOX WIRING (TOP OF CAR)

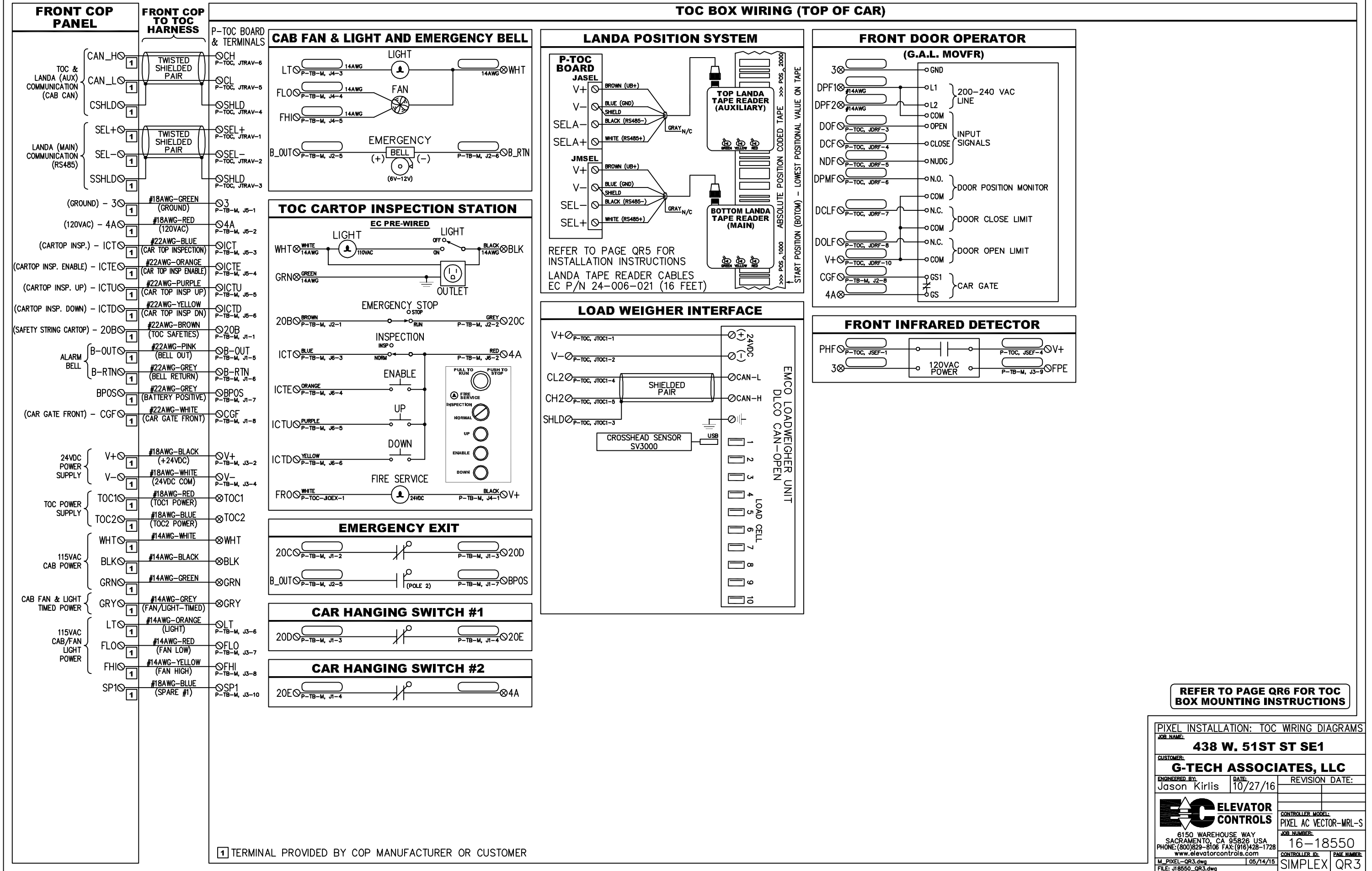


Diagram 10-10 shows the interlocking of the emergency power and normal power systems. The emergency power system is controlled by the EPI (Emergency Power Interlocking) switch, which is normally closed (NC) for normal power and normally open (NO) for emergency power. The normal power system is controlled by the EPTC (Emergency Power Transfer Control) switch, which is normally open (NO) for normal power and normally closed (NC) for emergency power. The interlocking is achieved by the EPI switch being in series with the EPTC switch. When the EPI switch is closed, the EPTC switch is open, and vice versa. This ensures that the emergency power system is always available when the normal power system is not operating.

Terminal Block Connections:

- 30 P-TB-H → ○1 (COM)
- 500 P-TB-H → ○2 (V+)
- DU30 P-TB-H → ○3 (DATA)

FACP Schematic: A schematic diagram of the Fire Alarm Control Panel (FACP) showing internal components and their connections to the terminal block.

Wiring Details:

- DOOR OPEN JEWEL:** DOLOF₀₂ (P-CNEX) → 24VDC → P-CNEX → V+_{T5}
- DOOR CLOSE JEWEL:** DCLOF₀₃ (P-CNEX) → 24VDC → P-CNEX → V+_{T5}
- SYSTEM TROUBLE JEWEL:** HCR0₀₄ (P-CNEX) → 24VDC → P-CNEX → V+_{T5}
- CAR TO LOBBY:** CTL₁₁ (P-CNEX) → OFF (O) → ON → P-CNEX → V+_{T5}
- EMERGENCY POWER JEWEL:** EPL0₁₂ (P-TB-M) → 24VDC → P-TB-H → 50
- FIRE SERVICE:** F102₀₁ (P-TB-M) → 24VDC → P-TB-H → 50
- ADDITIONAL FIRE RECALL:** FON2₀₂ (P-TB-M) → OFF (O) → ON → P-TB-H → 50
- CARD READER OVERRIDE:** CMR0₁₁₂ (P-CNEX) → OFF (O) → ON → P-CNEX → V+_{T5}

FRONT TOP

FRONT INTERMEDIATE

FRONT BOTTOM

GOV P-TB-M P-TB-M 4A

(CONTACT CLOSES WHEN TENSION SHEAVE MALFUNCTIONS)

22A ⊗ ○ STOP ○ SAFCO

22⊗ ⊗22A
(OPEN 6" ABOVE FLOOR)

21D ⊗ ⊗ 22
(OPEN 6 " BELOW FLOOR)

21C ⊗ ⊗ 21D

21B 21C

21A ⊗ ⊗ 21B

SAFH STOP RUN 21A

FIRE ALARM INITIATING DEVICES

MAIN FLOOR

FRAO 50F

(RETURNS CAR(S) TO THE ALTERNATE FIRE RECALL FLOOR)

**ALL FLOORS
EXCEPT MAIN**

FRSO 50F

(RETURNS CAR(S) TO THE MAIN FIRE RECALL FLOOR)

**HOISTWAY OR
MACHINE ROOM**

HF1O 50F

(RETURNS CAR(S) TO THE MAIN FIRE RECALL FLOOR)
& FLASHES COP FIRE INDICATOR(S) "85X")

**HOISTWAY OR
MACHINE ROOM**

HF2O 50F

(RETURNS CAR(S) TO THE ALTERNATE FIRE RECALL FLOOR)
& FLASHES COP FIRE INDICATOR(S) "85X")

30 P-TB-H — o1 (COM)
500 P-TB-H — o2 (V+)
DU30 P-TB-H — o3 (DATA)

SIMILAR CONNECTIONS FOR C.E.E. SERIAL FIXTURES (MICROCOMM) LOCATED IN THE HALL

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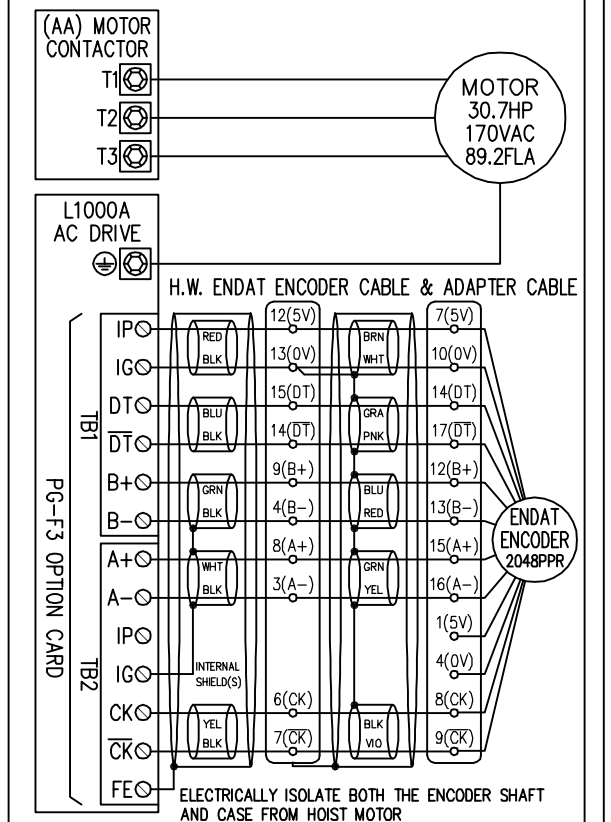
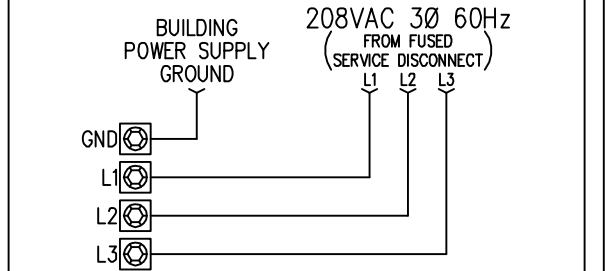
35 #18 AWG

SHIELD

1 CAT5e CABLE

E POINT ONLY.

NOTES:
CONDUCTORS MUST HAVE AN AMPACITY RATING
IN ACCORDANCE WITH TABLE 310.16 (COPPER/75°C)
OF THE NATIONAL ELECTRICAL CODE
DO NOT ROUTE INCOMING CONTROLLER POWER
OR MOTOR WIRES NEAR PRINTED CIRCUIT BOARDS
REFER TO HOIST MOTOR DATA PLATE &
MANUAL FOR PROPER MOTOR LEAD WIRING.

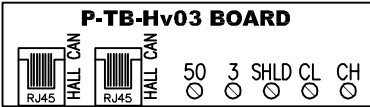


FLOOR OPENINGS			
BLDG. LDG.	FLOOR LABEL	SIMPLEX (ELEV. SET)	
		F	R
7	R	X	
6	5	X	
5	4	X	
4	3	X	
3	2	X	
*2	L	X	
1	C	X	
SPEED:		350fpm	
CAPACITY:		4,500lbs	

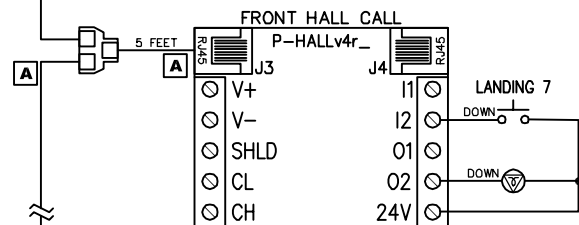
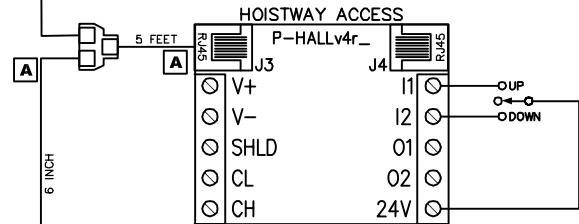
1 TERMINAL IS NOT PROVIDED IN CONTROLLER. REFERENCE POINT ONLY.

PIXEL INSTALLATION: HOISTWAY & MACHINE ROOM WIRING DIAGRAMS			
JOB NAME:			
438 W. 51ST ST SE1			
CUSTOMER:			
G-TECH ASSOCIATES, LLC			
ENGINEERED BY:	DATE:	REVISION DATE:	
Jason Kirlis	10/27/16	02/15/2017 JPK	
 ELEVATOR CONTROLS 6150 WAREHOUSE WAY SACRAMENTO, CA 95826 USA PHONE: (800)820-8106 FAX: (916)428-1728 www.elevatorcontrols.com		CONTROLLER MODEL:	
		PIXEL AC VECTOR-MRL-S	
		JOB NUMBER:	
		16-18550	
M_PIXEL-QR4.dwg	09/22/16	CONTROLLER ID:	PAGE NUMBER:
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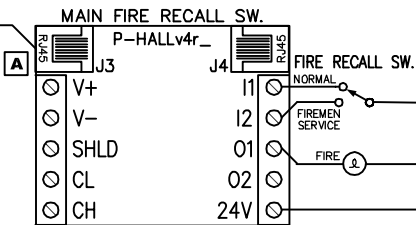
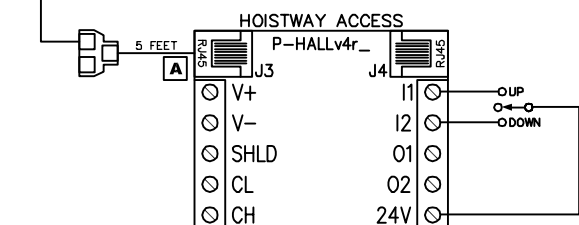
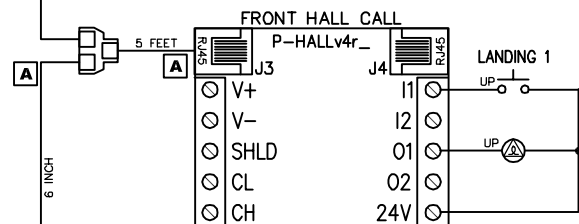
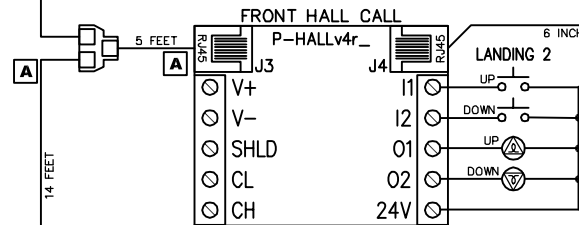
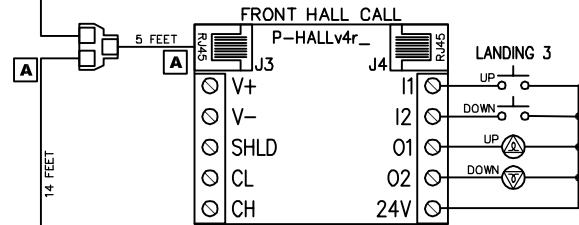
TYPICAL P-HALL BOARD INTERCONNECTIONS



- A** HALL CAN COMMUNICATION CABLES ARE CAT5e TERMINATED WITH RJ45 CONNECTOR AND WIRED TO 568-B STANDARDS.
1. CONNECT THE HALL CALL FIXTURE TO THE P-HALL BOARD I/O AS SHOWN BELOW.
 2. CONFIGURE THE P-HALL BOARD DIP SWITCH SETTINGS FOR THE CORRESPONDING HALL FIXTURE. (REFERENCE P-HALL CONFIGURATION TABLE)
 3. USING HALL CAN CABLES AND SPLITTERS TO INTERCONNECT THE P-HALL BOARDS AS SHOWN BELOW, THESE CABLES PROVIDE HALL CAN COMMUNICATION & POWER (24VDC/GND) TO EACH P-HALL BOARD.
 4. ALL SERIAL HALL FIXTURES MUST BE RATED 24VDC/0.5A MAX. PEAK/0.2A MAX. CONTINUOUS.



INTERMEDIATE LANDINGS
SIMILAR TO 3rd LANDING



QTY:	EC P/N:	PART DESCRIPTION:
10	17-002-114v04	P-HALLv04 BOARD
9	10-008-009	RJ45 SPLITTER
3	19-001-023-06in	CAN CABLE: 6 INCH
9	19-001-023-05ft	CAN CABLE: 5 FEET
0	19-001-023-07ft	CAN CABLE: 7 FEET
6	19-001-023-14ft	CAN CABLE: 14 FEET
1	19-001-023-25ft	CAN CABLE: 25 FEET
0	19-001-023-X	CAN CABLE: X FEET

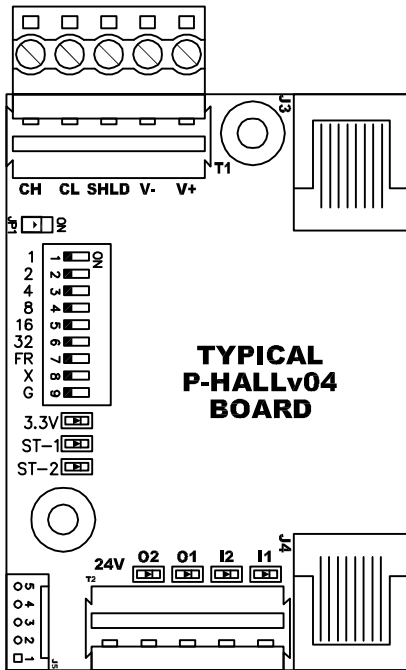
P-HALL BOARD CONFIGURATION TABLE

1. SET P-HALL BOARD DIP SWITCHES FOR THE RESPECTIVE LANDING NUMBER AND FUNCTION, USING THE BELOW CONFIGURATION TABLE.
2. SET P-HALL BOARD JP1 SWITCH FOR THE RESPECTIVE FUNCTION BY SLIDING THE SWITCH INTO THE APPROPRIATE POSITION, USING THE BELOW CONFIGURATION TABLE.

DIP SWITCHES (1) THRU (32) LANDING ADDRESS SELECTION				DIP SWITCHES (FR), (X) & (G) FUNCTION SELECTION		
LANDING NUMBER	JP1 IS OFF	FLOOR DESIGNATION	HALL CALL	HOSPITAL CALL	HALL LANTERN	
	JP1	1 2 4 8 16 32 EE X G	EE X G	EE X G	EE X G	

7	JP1	1 2 4 8 16 32 EE X G
6	JP1	1 2 4 8 16 32 EE X G
5	JP1	1 2 4 8 16 32 EE X G
4	JP1	1 2 4 8 16 32 EE X G
3	JP1	1 2 4 8 16 32 EE X G
2	JP1	1 2 4 8 16 32 EE X G
1	JP1	1 2 4 8 16 32 EE X G

DIP SWITCHES (1) thru (G) FUNCTION SELECTION			
LANDING NUMBER	MISCELLANEOUS FUNCTIONS	JP1 IS ON	FUNCTION SETTINGS
7	HOISTWAY ACCESS TOP	JP1	1 2 4 8 16 32 EE X G
1	HOISTWAY ACCESS BOTTOM	JP1	1 2 4 8 16 32 EE X G
2	MAIN FIRE RECALL	JP1	1 2 4 8 16 32 EE X G



DIMENSIONS (W/ CONNECTORS)
4"H X 2 1/8"W 7/8"D

FRONT P-HALL HOISTWAY WIRING DIAGRAMS

JOB NAME: **438 W. 51ST ST SE1**

CUSTOMER: **G-TECH ASSOCIATES, LLC**

ENGINEERED BY: Jason Kirlis DATE: 10/27/16

REVISION DATE:

ELEVATOR CONTROLS

6150 WAREHOUSE WAY
SACRAMENTO, CA 95828 USA
PHONE: (800)829-8106 FAX: (916)428-1728
www.elevatorcontrols.com

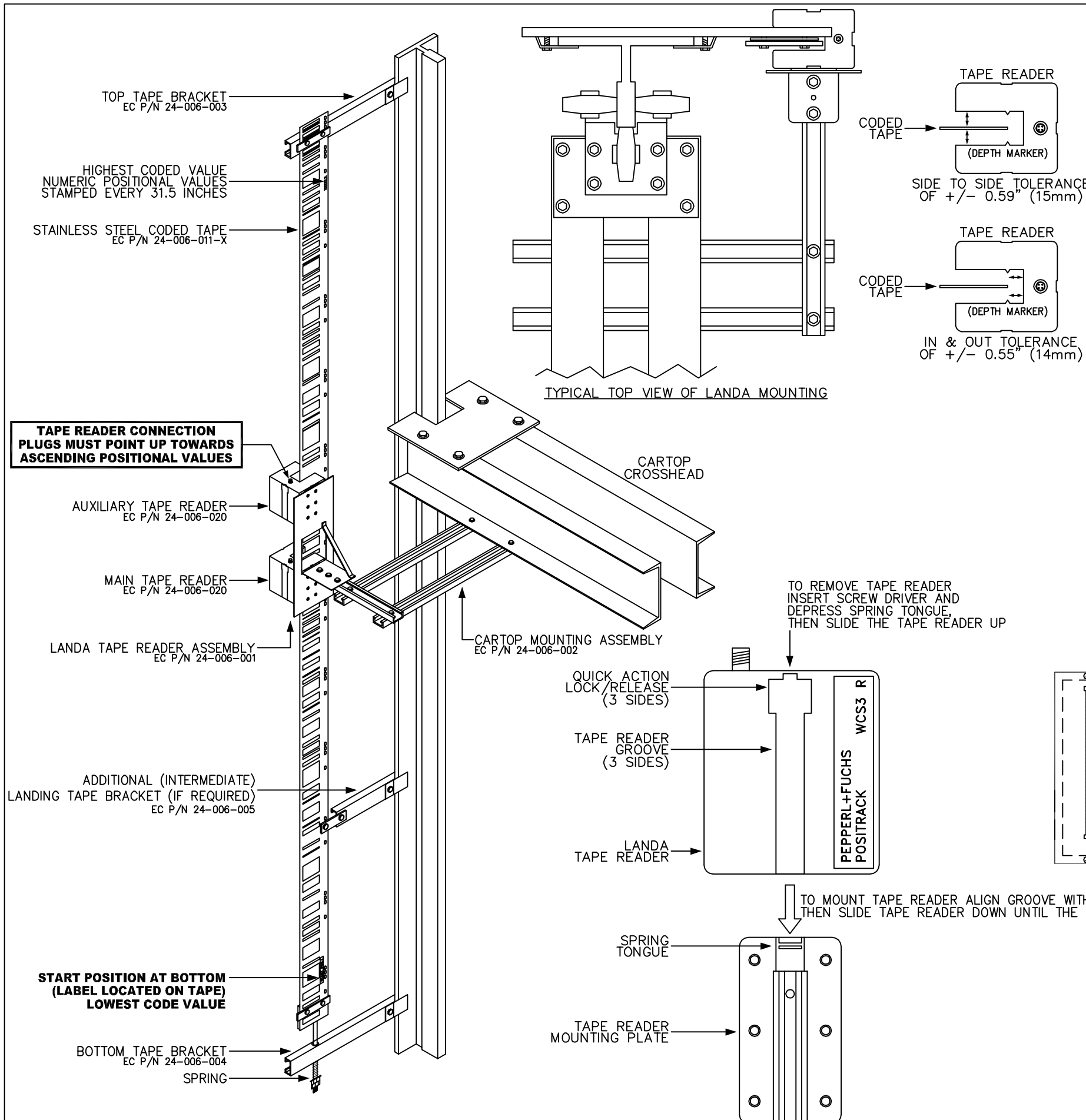
M_PIXEL-QR4b.dwg DATE: 03/24/16

FILE: J18550_QR4b.dwg

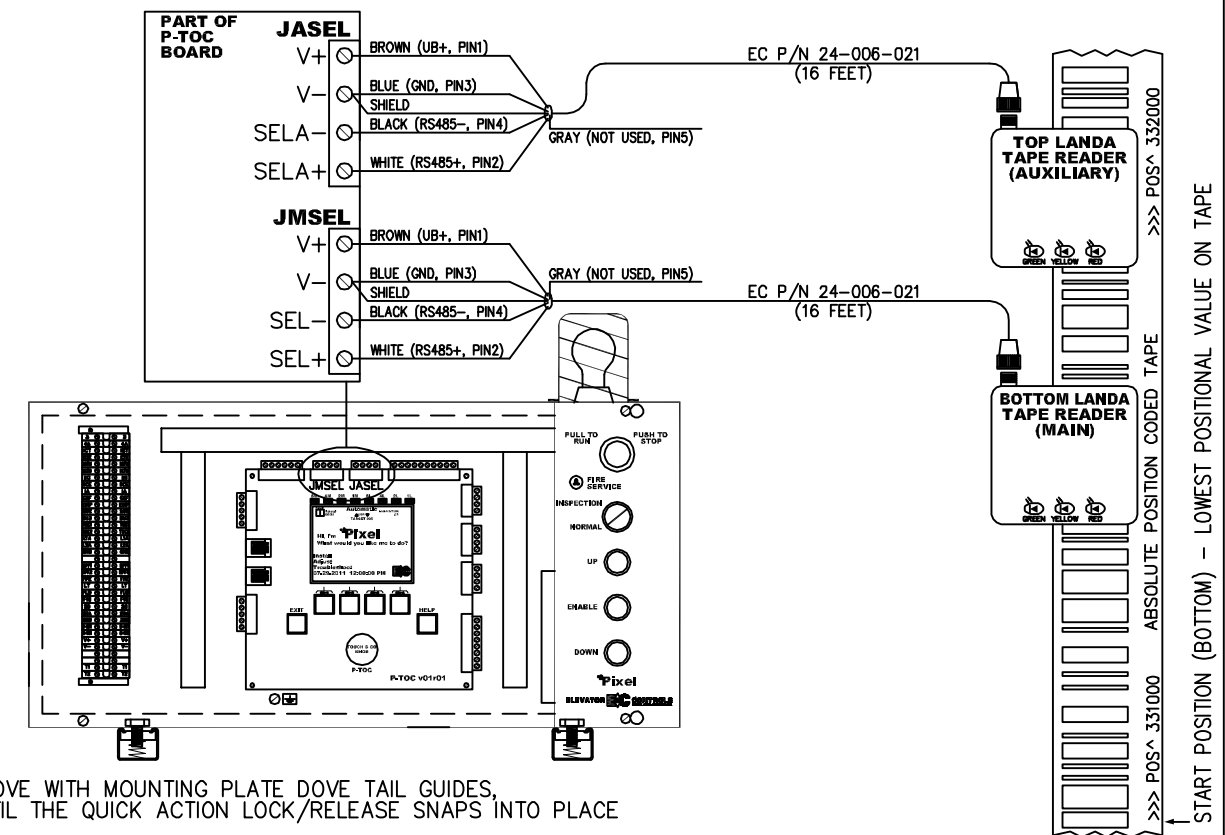
CONTROLLER MODEL: **PIXEL AC VECTOR-MRL-S**

JOB NUMBER: **16-18550**

CONTROLLER ID: **SIMPLEX** PAGE NUMBER: **QR4b**



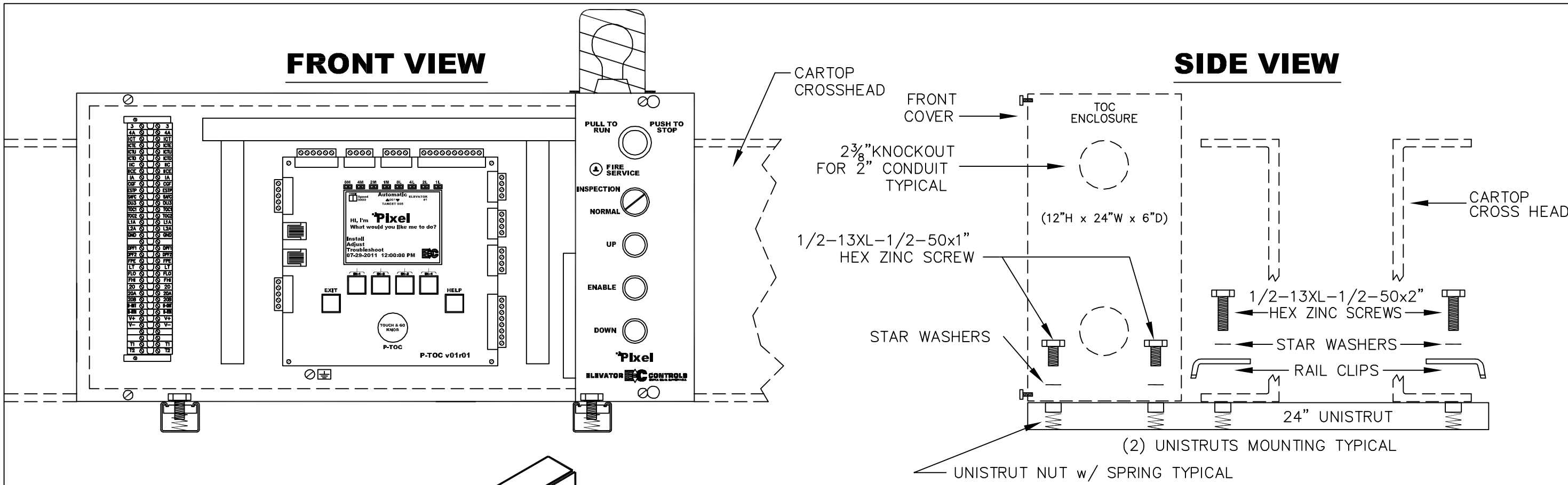
- INSTALLATION:**
- 1 ATTACH TOP AND BOTTOM TAPE BRACKETS TO RAIL USING CLIPS AND HARDWARE PROVIDED.
 - 2 HANG STAINLESS STEEL CODED TAPE FROM TAPE BRACKETS. VERIFY START POINT (LOWEST POSITIONAL VALUE) IS AT BOTTOM. THE TAPE HAS POSITIONAL VALUES STAMPED INTO THE TAPE EVERY 31.5 INCHES.
 - 3 ADJUST TAPE BRACKETS SO THE STAINLESS STEEL CODED TAPE IS IN PROPER VERTICAL ALIGNMENT (FRONT TO BACK AND SIDE TO SIDE).
 - 4 ADJUST THE SPRING ON THE BOTTOM TAPE BRACKET TO APPLY TENSION ONTO THE TAPE.
 - 5 MOUNT THE LANDA POSTION SYSTEM ONTO THE CARTOP USING UNISTRUTS AND HARDWARE (TYPICAL MOUNTING SHOWN TO THE LEFT).
 - 6 TAPE READER ORIENTATION CAN BE ADJUSTED BY USING THE QUICK ACTION LOCK/RELEASE FEATURE (SEE PICTURE BELOW)
 - 7 ALIGN TAPE READERS SO THAT THE TAPE IS CENTERED INSIDE READERS WHILE ALIGNED TO DEPTH MARKERS AT ANY POSITION IN THE HOISTWAY. TOLERANCES: $\pm 0.59"$ (15mm) SIDE TO SIDE AND $\pm 0.55"$ (14 mm) IN & OUT FROM CENTER OF TAPE READER.
 - 8 RUN THE CAR FROM TOP TO BOTTOM TO VERIFY THE ABOVE RUNNING TOLERANCES ARE NOT EXCEEDED AND ADJUST ACCORDINGLY.
 - 9 CONNECT THE BOTTOM TAPE READER (MAIN) TO THE P-TOC BOARD JMSL TERMINALS USING THE LANDA CABLE (EC P/N 24-006-021). TAPE READER PLUG ALWAYS POINTS UP TOWARD ASCENDING POSITION VALUE.
 - 10 CONNECT THE TOP TAPE READER (AUXILIARY) TO THE P-TOC BOARD JASEL TERMINALS USING THE LANDA CABLE (EC P/N 24-006-021). TAPE READER PLUG ALWAYS POINTS UP TOWARD ASCENDING POSITION VALUE..



PIXEL INSTALLATION: LANDA POSITION SYSTEM			
JOB NAME:			
438 W. 51ST ST SE1			
CUSTOMER:			
G-TECH ASSOCIATES, LLC			
ENGINEERED BY:	DATE:	REVISION DATE:	
Jason Kirlis	10/27/16		
		CONTROLLER MODEL:	
6150 WAREHOUSE WAY SACRAMENTO, CA 95828 USA PHONE: (800)829-8106 FAX: (916)428-1728 www.elevatorcontrols.com		PIXEL AC VECTOR-MRL-S	
M_PIXEL-QR5.dwg		JOB NUMBER:	16-18550
FILE: J18550_QR5.dwg		CONTROLLER ID:	SIMPLEX
		PAGE NUMBER:	QR5

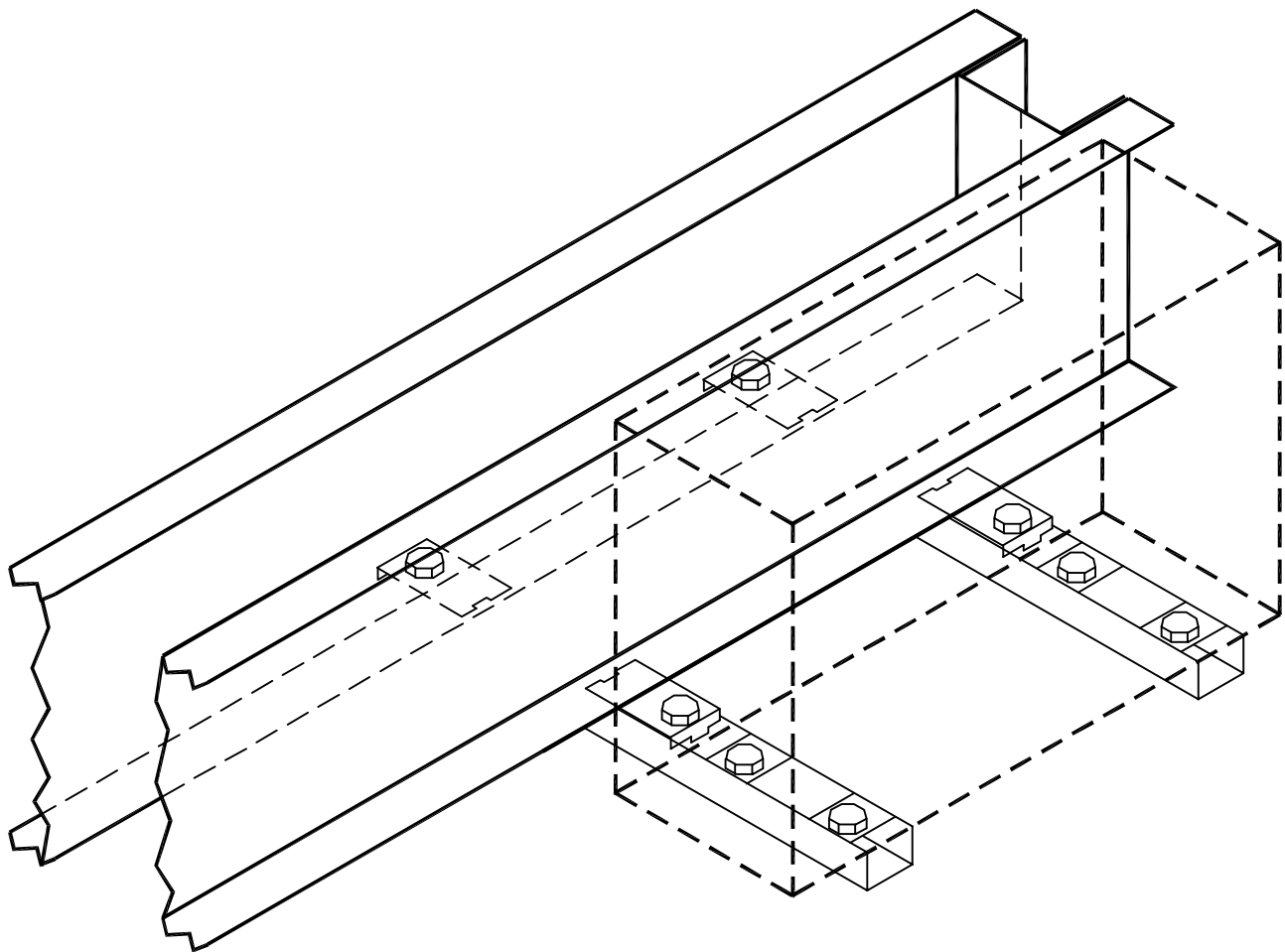
FRONT VIEW

SIDE VIEW



PIXEL TOC (TOP OF CAR) BOX MOUNTING INSTRUCTIONS

1. THE TOC BOX IS TYPICALLY MOUNTED TO THE CARTOP USING THE UNISTRUTS AND RAIL CLIPS (PROVIDED BY ELEVATOR CONTROLS), AS SHOWN IN THIS DIAGRAM. CHOOSE A MOUNTING LOCATION CLOSE TO THE LANDA POSITION SYSTEM (16 FOOT CABLES).
2. IF THIS MOUNTING TECHNIQUE CANNOT BE USED, IT IS UP TO THE INSTALLER TO MOUNT THE CARTOP ASSEMBLY PROPERLY. VERTICAL MOUNTING AS SHOWN, IS PREFERRED. WHEN MOUNTING HORIZONTALLY, CAUTION SHOULD BE TAKEN AGAINST METAL DEBRIS THAT CAN CAUSE ELECTRICAL DAMAGE.
3. SEVERAL KNOCKOUTS HAVE BEEN PROVIDED FOR 2" CONDUIT CONNECTIONS. CONNECT TRAVELING CABLE, SELECTOR, DOOR OPERATOR(S) AND COP USING THESE KNOCKOUTS.



PIXEL INSTALLATION: TOC (TOP OF CAR) BOX MOUNTING			
JOB NAME:			
438 W. 51ST ST SE1			
CUSTOMER:			
G-TECH ASSOCIATES, LLC			
ENGINEERED BY:	DATE:	REVISION DATE:	
Jason Kirlis	10/27/16		
ELEVATOR CONTROLS		CONTROLLER MODEL:	
6150 WAREHOUSE WAY		PIXEL AC VECTOR-MRL-S	
SACRAMENTO, CA 95828 USA		JOB NUMBER:	
PHONE: (800)829-8106 FAX: (916)428-1728		16-18550	
www.elevatorcontrols.com		CONTROLLER ID:	
M_PIXEL-QR6.dwg		PAGE NUMBER:	
FILE: J18550_QR6.dwg		SIMPLEX QR6	

Basic Start-up Procedure
1. Review and become familiar with the Yaskawa L1000A quick start guide, EC manuals and EC schematics
2. Verify all interconnections to the drive & controller are made in accordance with the EC schematic and Yaskawa L1000A quick start guide.
3. Verify the drive parameters marked with an " » " are correct and match the actual motor and job site data.
4. Use the <u>modified constants</u> menu in the drive to verify the EC parameter settings on this sheet. record any parameter changes in the field setting column.
5. AUTO-TUNING a permanent magnet (PM) motor- is a 3 step process, stationary auto tuning, initial magnet pole search and PG encoder offset. a. Move one of the jumper legs from H1 to HC terminal (two legs are both installed into H1 terminal on the L1000A drive) terminals HC, H1 & H2 are now jumped together to enable drive hardware b. Set H1-08=F, to disable base block c. Set C5-01=3 and C5-19=3, to reduce drive response gains d. If the landa positioning system is not installed, place the controller on construction mode (install menu) e. Set T2-01 = 1 and enter the required auto-tuning data (refer to E5-02, E1-05, E5-03, E5-04 and F1-01 for data) press the up key until "tuning ready?" is displayed f. Using controller insp., press both the up & enable buttons continue to press both buttons until auto-tune is complete g. Press the run key and the keypad will display "tune proceeding" until process is complete = "tune successful" h. Auto-tuning for initial magnet pole search with T2-01 = 3 repeat steps f & g (above) i. Rotational or stationary encoder offset auto-tuning: rotational (preferred method & most accurate) 1) Rotational encoder offset (ropes must be removed) Set H2-01 = 6 (Drive Ready), allows brake to lift Set T2-01 = 10 and repeat steps f & g (above) Set T2-01 = 11 and repeat steps e & f (above) Restore H2-01 = 0 (Drive Run) 2) Stationary encoder offset Set T2-01 = 4 and repeat steps f & g (above) j. Remove jumper from terminal HC and restore H1-08=9, C5-01=15 & C5-19=15 k. Record encoder offset (E5-11) in field setting column Rotational auto-tuning notes: If the motor rotates in the opposite direction, change B1-14 from 0 to 1. this switches the phase order to U-W-V. Encoder setup: Rotate the motor and check parameter U1-05 (Speed Feedback). verify the value is positive in the up and negative in the down direction. change F1-05 from 1 to 0 if the values are reversed.
Basic Adjustment Procedure
1. For contract speed calibration refer to section A2.5 of the Pixel traction controller installation and adjustment manual.
2. Contract speed-response and control: If slow response during acceleration, increase C5-01 then shorten C5-02. If vibration occurs, decrease C5-01 then lengthen C5-02.
3. Starting-response and rollback control: If rollback occurs after the brake is lifted, increase C5-19 & S3-39 then shorten C5-20. if vibration occurs, decrease C5-19 & S3-39 then lengthen C5-20. If rollback persists, increase S3-02 in small adjustments. If required increase S3-01 in small adjustments.
4. Stopping-response and control: If stopping with poor accuracy, check analog pattern, jerk and deceleration rates. Increase S3-03 in small adjustments. If vibration occurs, decrease S3-03. Increase S1-05 if additional brake engagement time is required.
Saving And Uploading Parameters
After completely setting up the drive parameters, save the values as user-set defaults by setting 02-03 = 1 and pressing the enter key. The display will return to 0. To restore values saved in user-set defaults (02-03), set A1-03 = 1110 (uploads only the parameters saved in 02-03)

L1000A CLOSED LOOP FLUX VECTOR, PIXEL VECTOR AC FOR PM MOTOR CONTROLLERS							
Number	Parameter Name	Unit	Range	Default	EC Setting	Field Setting	Notes
A1-01	Access Level Selection	-	0-2	2	2		2=Adv. Access
A1-02	Control Method Selection	-	0,2,3,7	2	7		7=C.L. PM Motor
b1-01	Speed Reference Selection	-	0-3	0	2		2=MOD BUS
b1-02	Up/Down Command Selection	-	0-3	1	2		2=MOD BUS
» b1-14	Phase Order Selection	-	0-1	0	0		0=U-V-W
C1-01	Acceleration Ramp 1	SEC	0.00-600.00	1.50	1.00		
C1-02	Deceleration Ramp 1	SEC	0.00-600.00	1.50	0.20		
C1-03	Acceleration Ramp 2	SEC	0.00-600.00	1.50	0.00		
C1-04	Deceleration Ramp 2	SEC	0.00-600.00	1.50	0.00		
C1-09	Fast Stop Ramp	SEC	0.00-600.00	1.50	0.50		
C2-01	Jerk At Accel Start	SEC	0.00-10.00	0.50	0.00		
C2-02	Jerk At Accel End	SEC	0.00-10.00	0.50	0.00		
C2-03	Jerk At Decel Start	SEC	0.00-10.00	0.50	0.00		
C2-04	Jerk At Decel End	SEC	0.00-10.00	0.50	0.00		
C2-05	Jerk Below Leveling Speed	SEC	0.00-10.00	0.50	0.00		
C5-01	Spd Cntrl Lp Proportional Gain 1	-	0.00-300.00	3.00	10.00		
C5-02	Spd Cntrl Lp Integral Time 1	SEC	0.000-10.000	0.30	0.50		
C5-03	Spd Cntrl Lp Proportional Gain 2	-	0.00-300.00	3.00	10.00		On if C5-07 > 0
C5-04	Spd Cntrl Lp Integral Time 2	SEC	0.000-10.000	0.30	0.50		On if C5-07 > 0
C5-07	Spd Cntrl Settings Switching Speed	%	0.0-100.0	2	0		0=Disable C5-03/04
C5-13	Spd Cntrl Lp Proportional Gain 3	-	0.00-300.00	3.00	10.00		On if C5-07 > 0
C5-14	Spd Cntrl Lp Integral Time 3	SEC	0.000-10.000	0.30	0.50		On if C5-07 > 0
C5-17	Motor Inertia	kgm ²	0.0001-600.00	B	A		
C5-19	Spd Cntrl Lp Proportional Gain During Position Lock	-	0.00-300.00	10.00	10.00		
C5-20	Spd Cntrl Lp Integral Time During Position Lock	SEC	0.000-10.000	0.10	0.50		
C6-03	Carrier Frequency	kHz	1.0-15.0	B	8		
C6-06	PWM Method	-	0-2	0	0		0=2/3-PH Conversion
» E1-01	Input Voltage Setting	V	155-255	230	208		
» E1-04	Maximum Output Frequency	Hz	4.0-120.0	60	41.6		
» E1-05	Maximum Voltage (Motor)	V	0.0-255	200	170		
» E1-06	Base Frequency (Motor)	Hz	0.0-120.0	60	41.6		Equal To E1-04
» E5-02	Motor Rated Power	kW	0.10-650.00	B	22.90		kW = HP x 0.746
» E5-03	Motor Rated Current	A	10-200% Rating	B	89.2		Rating= B
» E5-04	Number Of Motor Poles	#POLES	2-48	12	28		
E5-05	Motor Stator Resistance (Single Phase)	Ω	0.000-65.000	B	A		
E5-06	Motor D-axis Inductance	mH	0.00-600.00	B	A		
E5-07	Motor Q-axis Inductance	mH	0.00-600.00	B	A		
E5-09	Motor Induction Voltage Constant 1	mV/(rad/SEC)	0.0-6500.0	B	A		
E5-11	Encoder Offset	DEG	-180-180	0.0	A		
E5-24	Motor Induction Voltage Constant 2	mV/(r/MIN)	0.0-6500.0	0.0	A		
» F1-01	Encoder 1 Resolution	PPR	1-60000	2048	2048		
F1-02	Operation Sel. At PG Open Circuit (PGO)	-	0-3	1	0		0=Ramp To Stop
F1-03	Operation Selection At Overspeed	-	0-3	1	0		0=Ramp To Stop
F1-04	Operation Selection At Deviation	-	0-3	3	0		0=Ramp To Stop
» F1-05	Encoder 1 Rotation Direction Selection	-	0,1	1	1		
F1-10	Excessive Speed Deviation Detection Level	%	0-50	10	25		
F1-19	DV4 Detection Selection	-	0-5000	128	0		0=Disabled
H1-03	Terminal S3 Function Selection	-	Multi-function	24	20		20=Ext Flt Ramp To Stop
H1-04	Terminal S4 Function Selection	-		14	F		F=Not Used
H1-05	Terminal S5 Function Selection	-		3	F		F=Not Used
H1-06	Terminal S6 Function Selection	-		4	F		F=Not Used
H1-07	Terminal S7 Function Selection	-	Digital Inputs	5	15		15=Fast Stop N.O.
H1-08	Terminal S8 Function Selection	-		F	9		9=Baseblock N.C.
H2-01	Terminal M1-M2 Function Selection (relay)	-	& Digital Outputs	50	0		0=During Run
H2-02	Terminal M3-M4 Function Selection (relay)	-		51	F		F=Not Used
H2-03	Terminal M5-M6 Function Selection (relay)	-		6	F		F=Not Used
H3-02	Torque Compensation	-	0,2,3,14,1F	0	14		14=Pre-torque

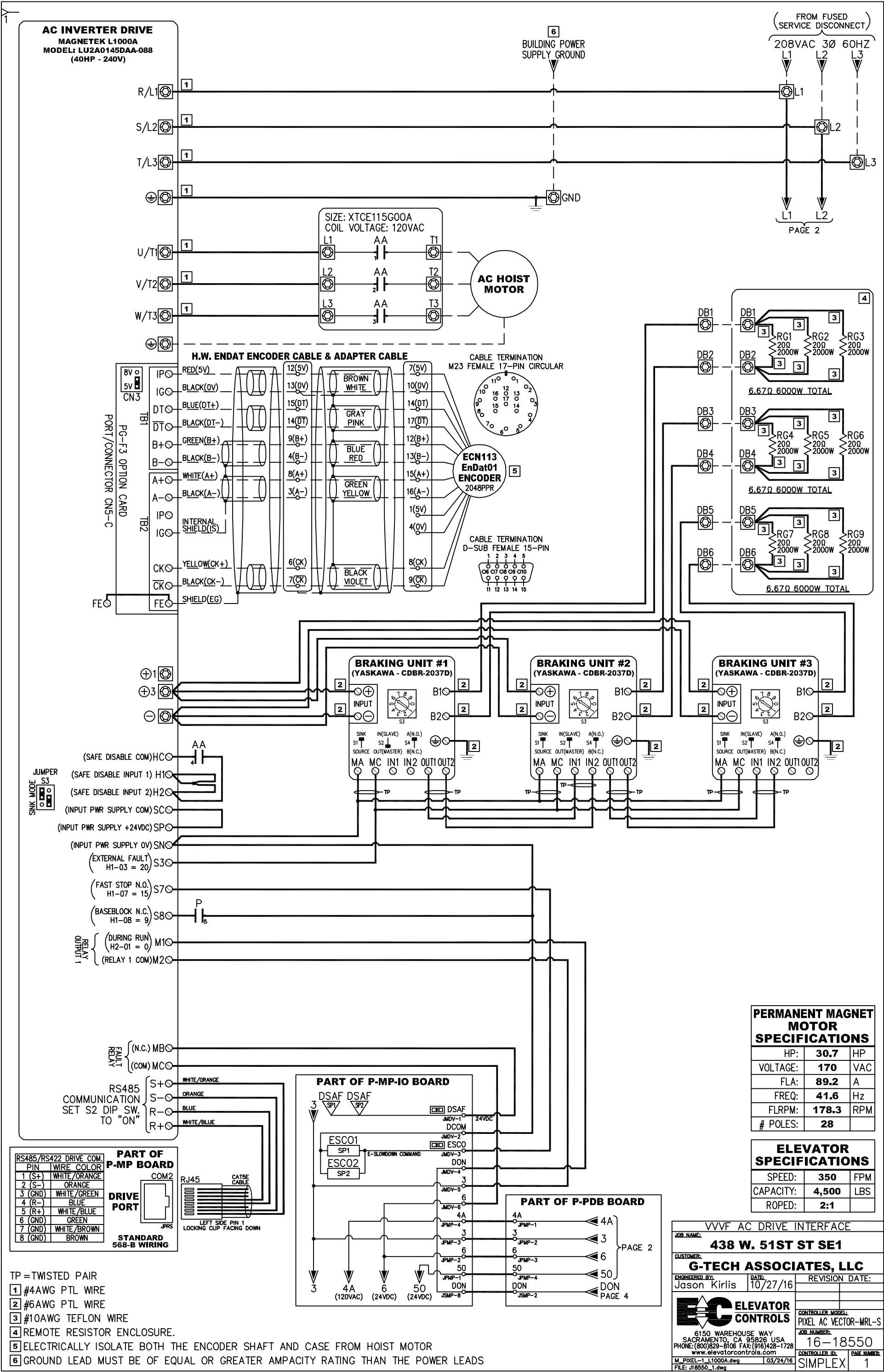
Number	Parameter Name	Unit	Range	Default	EC Setting	Field Setting	Notes
H5-02	Communication Speed Selection	-	0-8	3	8		8=115200bps
H5-11	Communications Enter Function Sel.	-	0,1	0	1		1=Enter Not Necessary
L5-01	Number Of Auto Reset Attempts	-	0-10	0	2		
L5-02	Fault Output Operation During Auto Reset	-	0,1	0	1		1=Active
L6-01	Torque Detection Selection 1	-	0-8	0	2		2=α3 Active During Run
L6-02	Torque Detection Level 1	%	0-300	150	200		
L7-01	Forward Torque Limit	%	0-300	200	300		
L7-02	Reverse Torque Limit	%	0-300	200	300		
L7-03	Forward Regenerative Torque Limit	%	0-300	200	300		
L7-04	Reverse Regenerative Torque Limit	%	0-300	200	300		
L8-05	Input Phase Loss Protection Selection	-	0-3	1	0		0=Disabled
L8-55	Internal Braking Transistor Protection	-	0,1	B	0		0=DISABLED
n8-62	Output Voltage Limit	V	0.0-230.0	200.0	188		E1-01 Minus 20v
o1-03	Digital Operator Display Unit Selection	-	0-6	1	1		1=0.01%
o1-04	V/f Pattern Setting Units	-	0,1	1	0		0=Hz, C.L. Only
o1-12	Length Units	-	0,1	0	1		1=Inches
» o1-20	Traction Sheave Diameter	INCH	3.70-78.00	15.70	15.00		
» o1-21	Roping Ratio	-	1-4	2	2		2=2:1
» o1-22	Mechanical Gear Ratio	-	0.10-50.00	1.00	1.00		
P1-01	-	-	-	-	AC		
P1-02	-	-	-	-	26		
P1-03	-	-	-	-	45		
P1-04	-	-	-	-	4B		
S1-01	Zero Speed Level At Stop	%	0.000-9.999	0.350	0.350		
S1-04	Position Lock Time At Start	SEC	0.00-10.00	0.40	0.40		
S1-05	Position Lock Time At Stop	SEC	0.00-10.00	0.60	1.0		
S1-06	Brake Release Delay Time	SEC	0.00-10.00	0.20	0.00		
S1-07	Brake Close Delay Time	SEC	0.00-(S1-05)	0.10	0.10		
S1-10	Run Command Delay Time	SEC	0.00-1.00	0.10	0.10		
S3-01	Position Lock Gain At Start 1	-	0-100	5	15		
S3-02	Position Lock Gain At Start 2 (anti-rollback)	-	0.00-100.00	0.00	15		
S3-03	Position Lock Gain At Stop	-	0-100	5	5		
S3-10	Starting Torque Compensation Increase Time	mSEC	0-5000	500	200		
S3-14	Torque Compensation Fade Out Speed	%	0.0-100%	0.0	1		
S3-16	Torque Limit Reduction Time	mSEC	0-10000	100	200		
S3-27	Torque Compensation Value With Load Condition 1	%	-100%-100%	-50	-100		
S3-28	Torque Compensation Value With Load Condition 2	%	-100%-100%	50	100		
S3-29	Analog Input From Load Cell With Load Condition 1	%	-100%-100%	0	-100		
S3-39	Anti-rollback Integral Gain	-	-30.00-30.00	0.00	0.00		
S3-40	Anti-rollback Movement Detection	PULSE	0-100	1	1		
S3-41	Position Lock Gain At Start 2 Reduction	-	0.00-1.00	0.50	0.50		
S6-11	Overacceleration Detection Time	mSEC	0-5000	50	500		

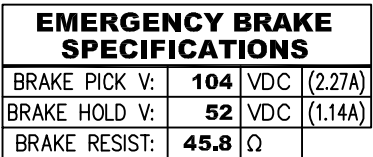
*** Pixel Parameters ***	
Speed Profile	
Pattern Delay (ms)	400ms
Ramp To Stop	YES
Releveling Offset (set to 40% Dead Zone)	0.0
Speed Pattern Scaling % (Jobs below 10Hz)	OFF
Motor/Brake Timers	
Brake Pick Delay (s)	0.2s
Brake Drop Delay (s)	0.2s
Zero Speed Hold Delay (s)	2.0s

A Parameter Is Modified During Auto-tuning Process
B o2-04 (Drive Model Selection) Dependent Parameters

Parameter Constrain Settings
Pattern Delay > = S1-04 Zero Speed Hold > S1-05 + S3-16 S1-04 > S3-10, and S1-05 > Brake Drop Delay Zero Speed Hold > Brake Drop Delay

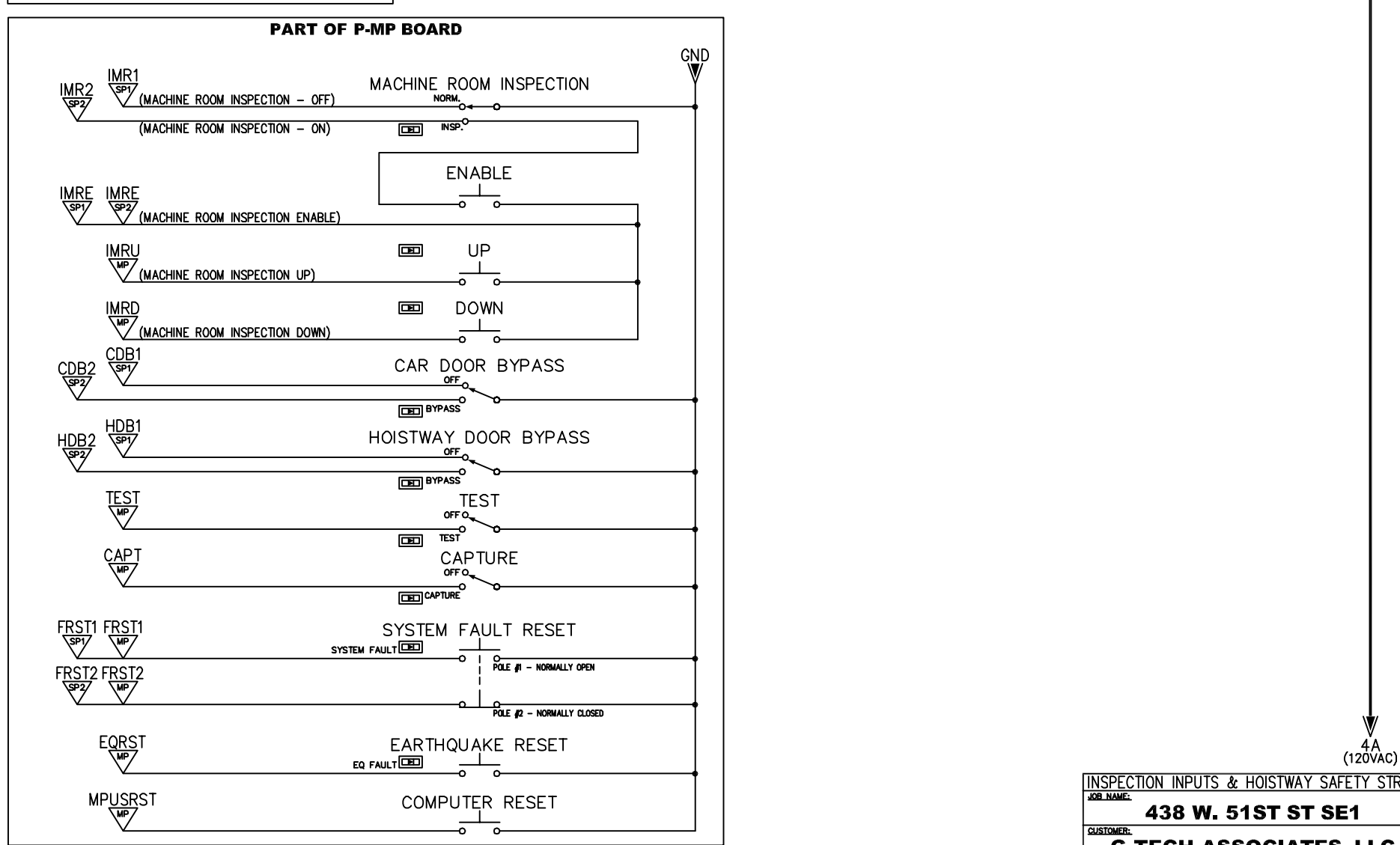
VVVF YASKAWA L1000A DRIVE PARAMETER LIST			
JOB NAME:			
438 W. 51ST ST SE1			
CUSTOMER:			
G-TECH ASSOCIATES, LLC			
ENGINEERED BY:	DATE:	REVISION DATE:	
Jason Kirlis	10/27/16		
		CONTROLLER MODEL:	
		PIXEL AC VECTOR-MRL-S	
6150 WAREHOUSE WAY SACRAMENTO, CA 95828 USA PHONE: (800)829-8106 FAX: (916)428-1728 www.elevatorcontrols.com		JOB NUMBER:	
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FILE: J18550_QR7.dwg		CONTROLLER ID:	PAGE NUMBER:
		SIMPLEX	QR7



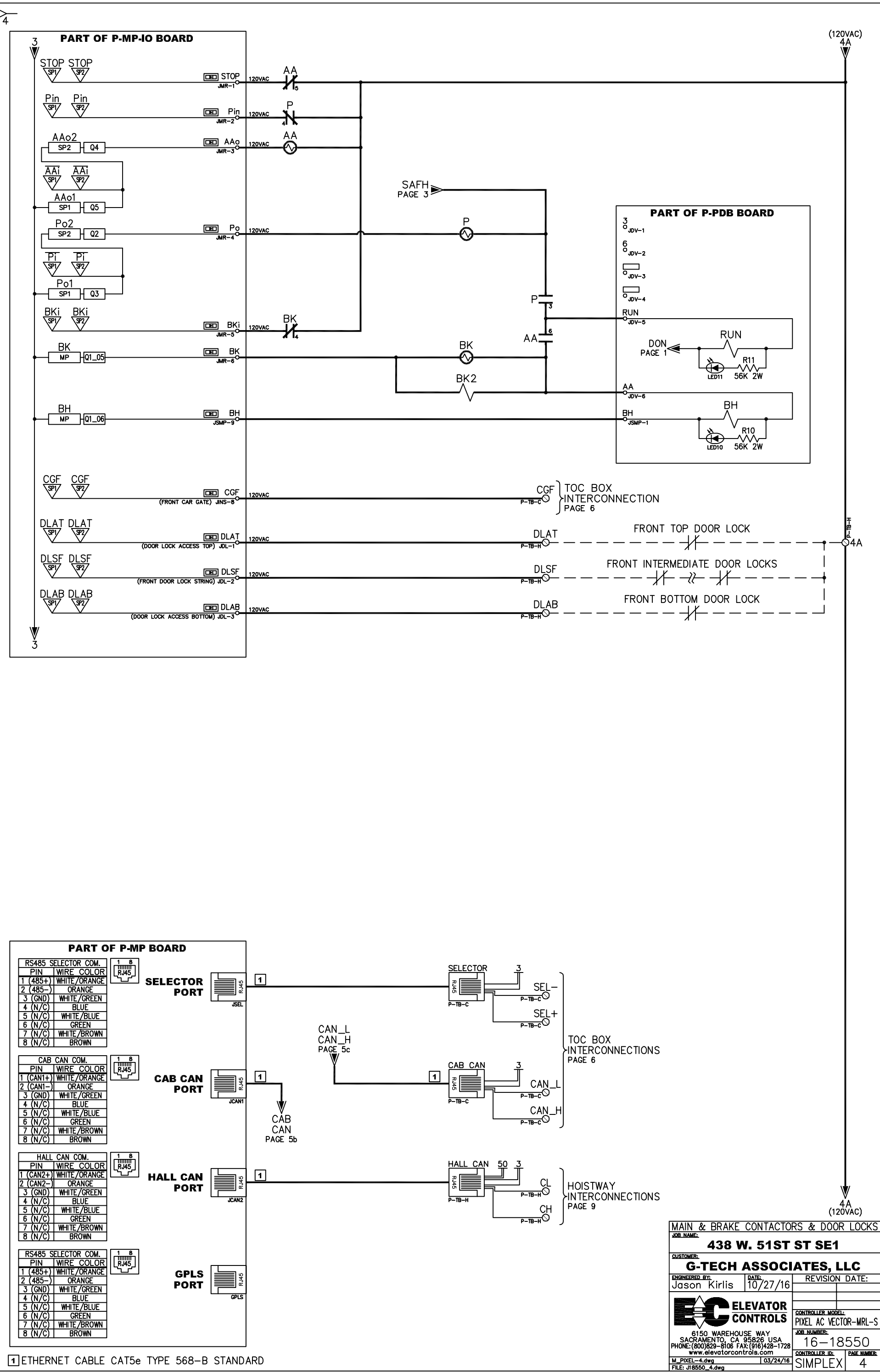


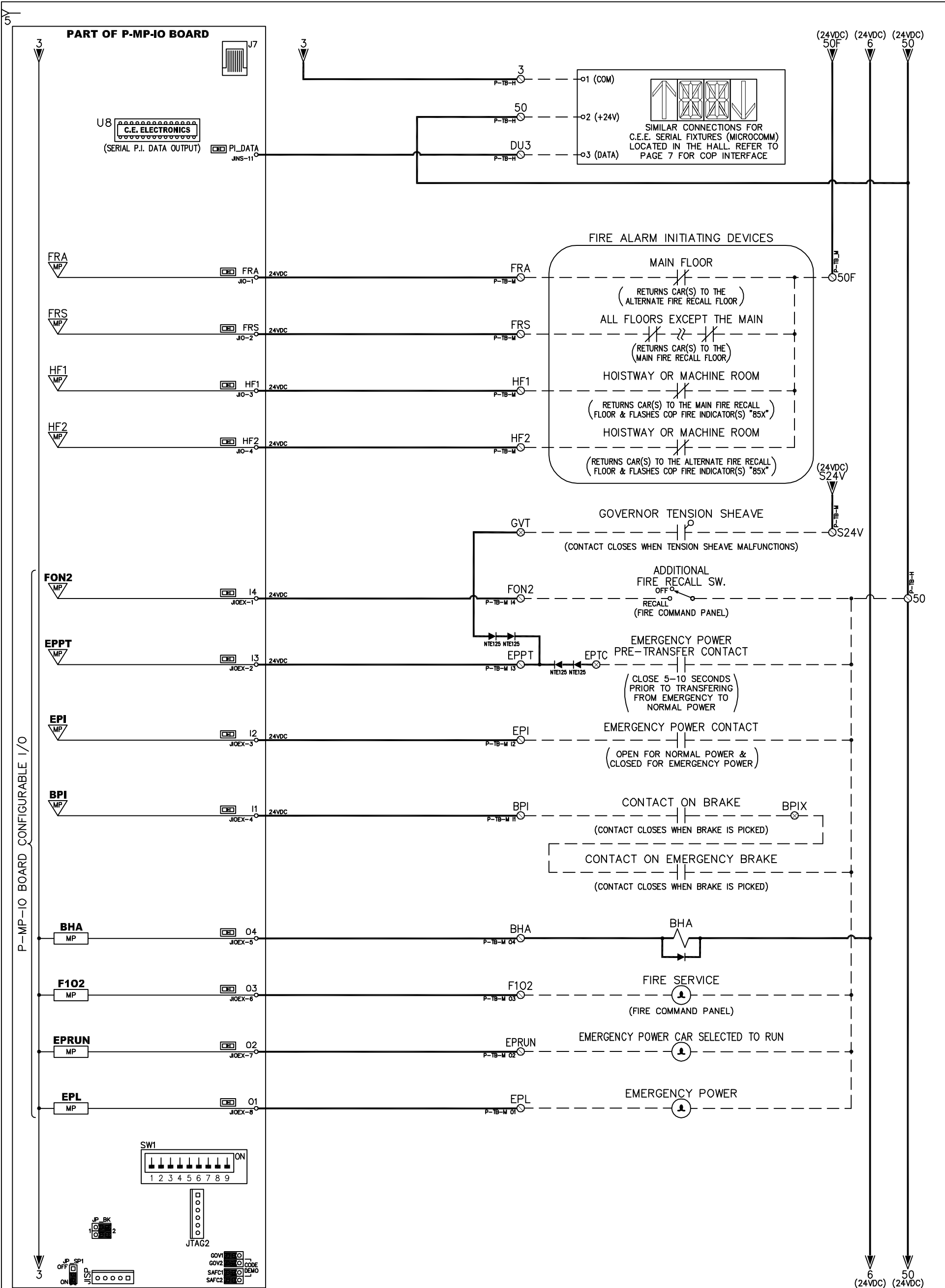
- | FUSE LIST | | | | | | | | | | | | | | | | | | |
|-----------|------------|-----|-----|-----|------|------|------|------|-----|-----|------|-------|------|------|--|--|--|--|
| FUSE TYPE | FUSES | | | | | | | | | | | | | | | | | |
| 500V FNQ | | | | | | | | | | | | | | | | | | |
| 250V MDA | FL1 | FL2 | FL3 | FL4 | FCT1 | FCT2 | FSP1 | FSP2 | FB1 | FB2 | FGP1 | FS24V | FFN1 | FFN2 | | | | |
| 250V AGC | ALL OTHERS | | | | | | | | | | | | | | | | | |

CONTROLLER POWER, BRAKE & EMERGENCY BRAKE			
JOB NAME:			
438 W. 51ST ST SE1			
CUSTOMER:			
G-TECH ASSOCIATES, LLC			
ENGINEERED BY:		DATE:	
Jason Kirlis		10/27/16	
		REVISION DATE:	
		CONTROLLER MODEL:	
		PIXEL AC VECTOR-MRL-S	
		JOB NUMBER:	
		16-18550	
		CONTROLLER ID:	
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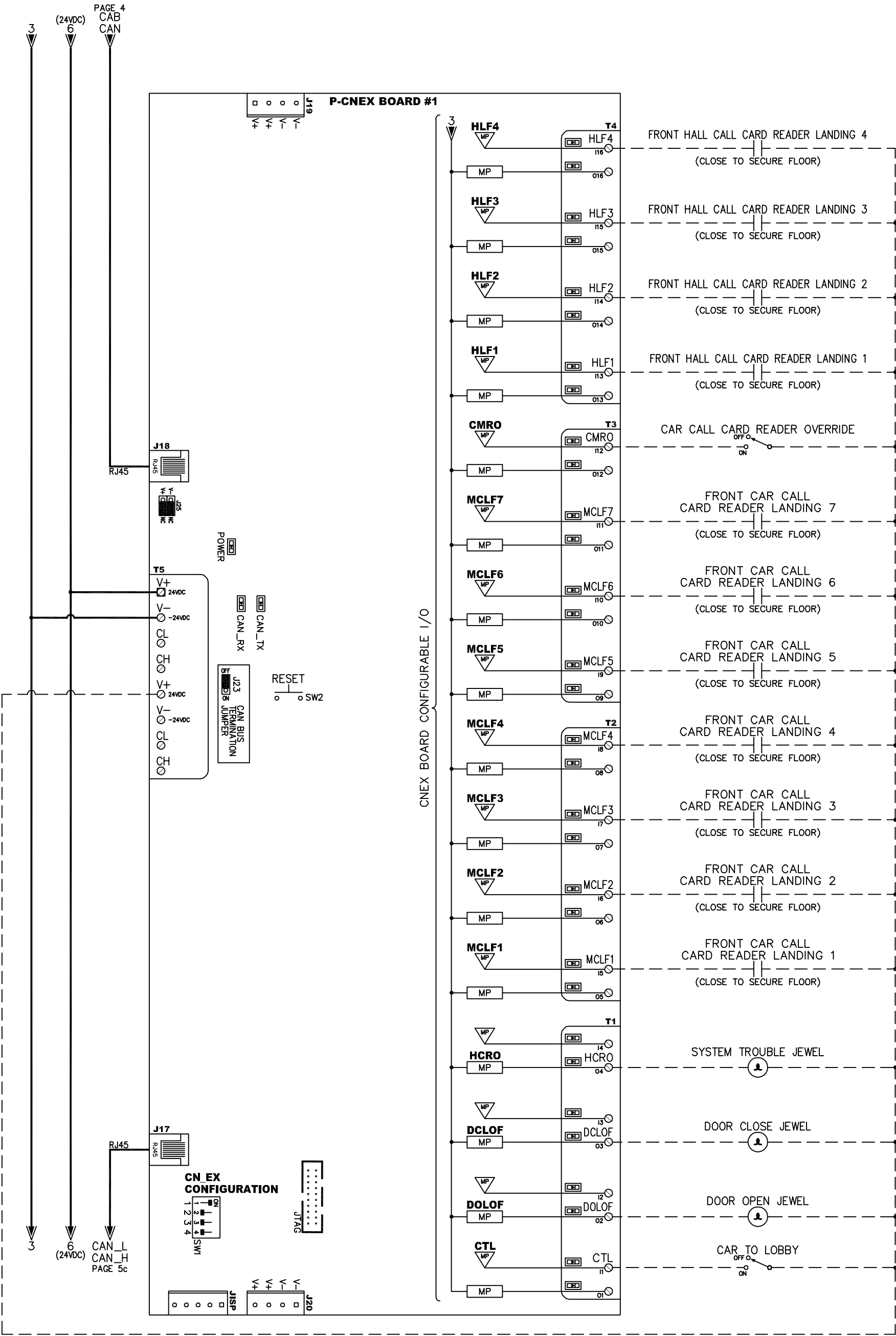


INSPECTION INPUTS & HOISTWAY SAFETY STRING				
JOB NAME:				
438 W. 51ST ST SE1				
CUSTOMER:				
G-TECH ASSOCIATES, LLC				
ENGINEERED BY:	DATE:	REVISION DATE:		
Jason Kirlis	10/27/16			
		CONTROLLER MODEL:		
		PIXEL AC VECTOR-MRL-S		
		JOB NUMBER:		
		16-18550		
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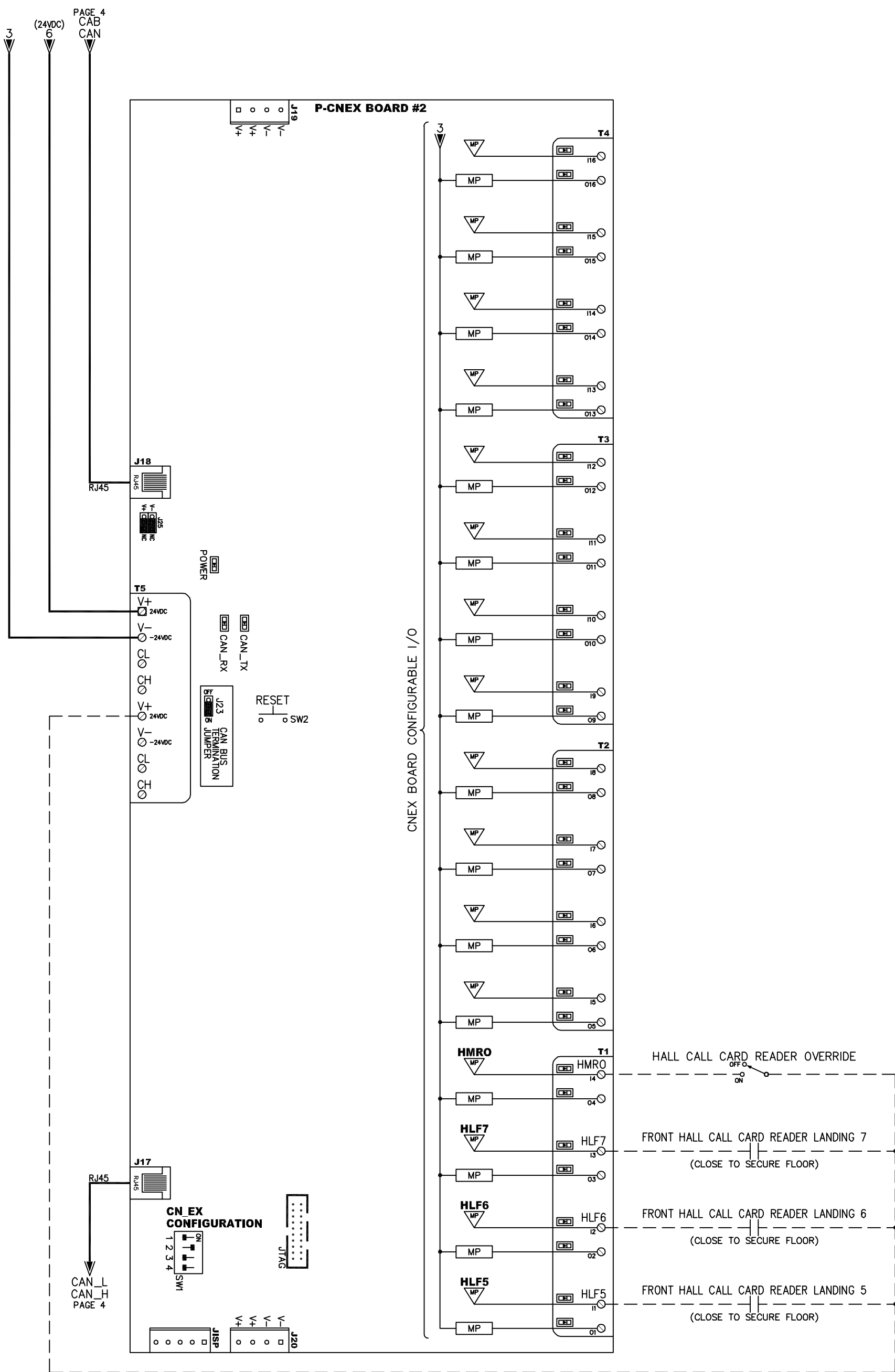




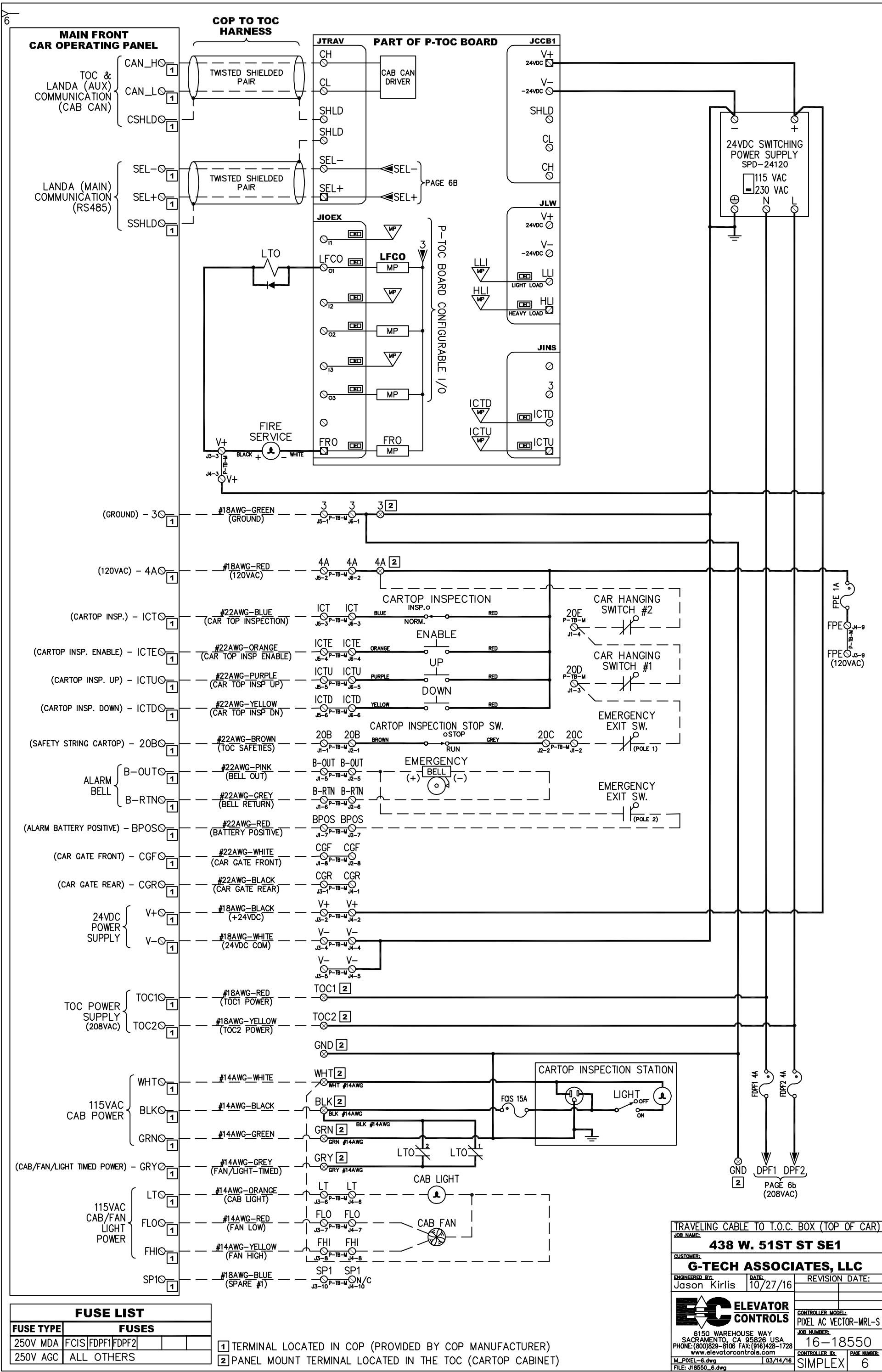
P-MP-IO BOARD - INPUTS/OUTPUTS			
JOB NAME:			
438 W. 51ST ST SE1			
CUSTOMER:			
G-TECH ASSOCIATES, LLC			
ENGINEERED BY:	DATE:	REVISION DATE:	
Jason Kirlis	10/27/16	02/15/2017 JPK	
		CONTROLLER MODEL:	
		PIXEL AC VECTOR-MRL-S	
		JOB NUMBER:	
		16-18550	
		CONTROLLER ID:	
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FILE: J18550 - 5-M1.dwg		SIMPLEX	5



MP P-CNEX BOARD – EXPANSION I/O			
JOB NAME:			
438 W. 51ST ST SE1			
CUSTOMER:			
G-TECH ASSOCIATES, LLC			
ENGINEERED BY:	DATE:	REVISION DATE:	
Jason Kirilis	10/27/16		
 ELEVATOR CONTROLS 6150 WAREHOUSE WAY SACRAMENTO, CA 95826 USA PHONE: (800)829-8108 FAX: (916)428-1728 www.elevatorcontrols.com		CONTROLLER MODEL:	
		PIXEL AC VECTOR-MRL-S	
		JOB NUMBER:	
		16-18550	
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FILE: J18550_5b.dwg		08/23/16	SIMPLEX 5b



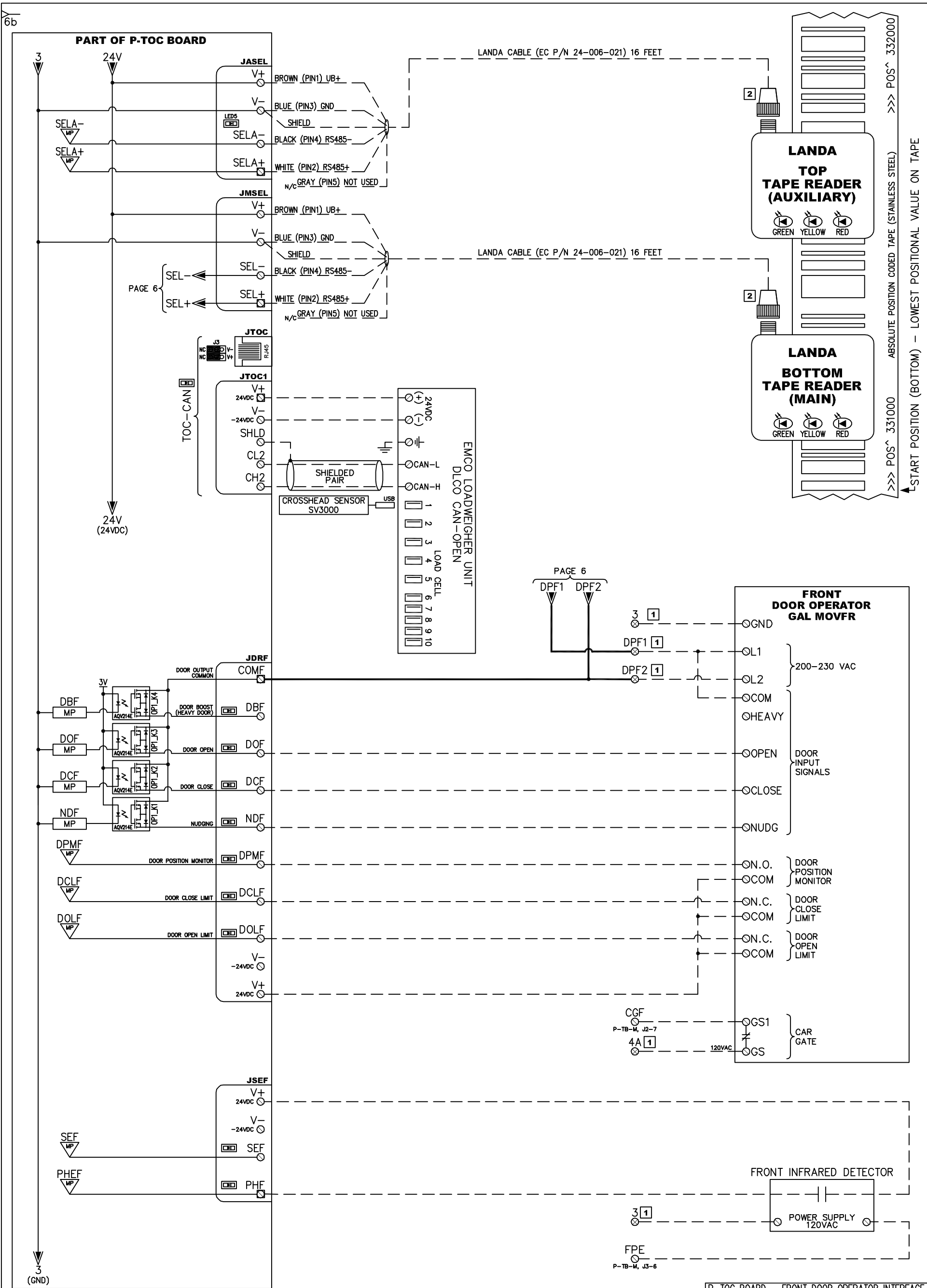
MP P-CNEX BOARD - EXPANSION 1/0			
JOB NAME: 438 W. 51ST ST SE1			
CUSTOMER: G-TECH ASSOCIATES, LLC			
ENGINEERED BY: Jason Kirlis		DATE: 10/27/16	
		REVISION DATE:	
			
		CONTROLLER MODEL: PIXEL AC VECTOR-MRL-S	
		JOB NUMBER: 16-18550	
6150 WAREHOUSE WAY SACRAMENTO, CA 95828 USA PHONE: (800)829-8108 FAX: (916)428-1728 www.elevatorcontrols.com		CONTROLLER ID: SIMPLEX	
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		08/23/16	



FUSE LIST

FUSE TYPE	FUSES
250V MDA	FCIS FDPF1 FDPF2
250V AGC	ALL OTHERS

- 1 TERMINAL LOCATED IN COP (PROVIDED BY COP MANUFACTURER)
- 2 PANEL MOUNT TERMINAL LOCATED IN THE TOC (CARTOP CABINET)



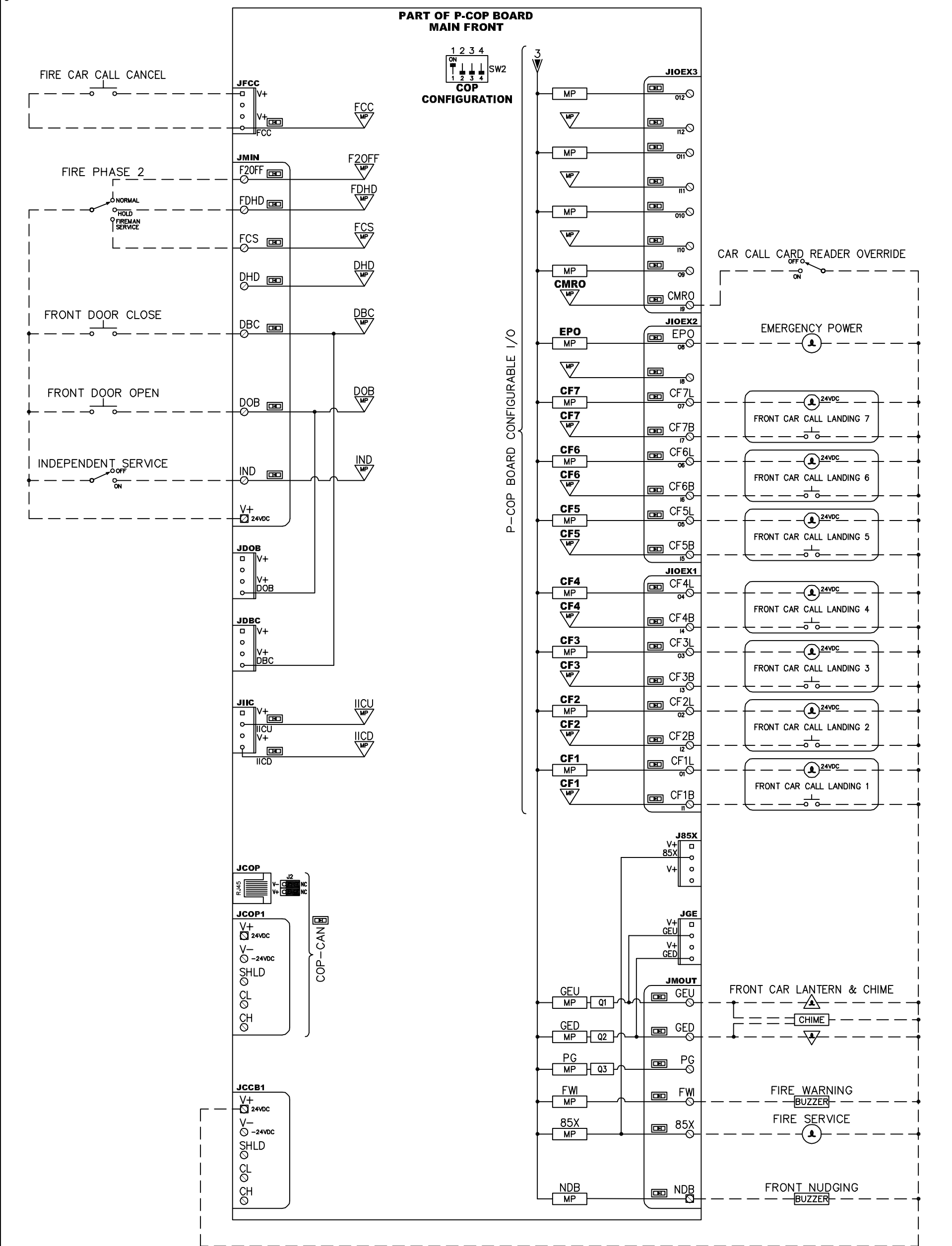
1 PANEL MOUNT TERMINAL LOCATED IN THE TOC (CARTOP CABINET)

2 REFER TO PAGE QR5 FOR LANDA POSITION SYSTEM INSTALLATION INSTRUCTIONS

P-TOC BOARD - FRONT DOOR OPERATOR INTERFACE			
JOB NAME:			
438 W. 51ST ST SE1			
CUSTOMER:			
G-TECH ASSOCIATES, LLC			
ENGINEERED BY:	DATE:	REVISION DATE:	
Jason Kirilis	10/27/16		
		CONTROLLER MODEL:	
		PIXEL AC VECTOR-MRL-S	
6150 WAREHOUSE WAY SACRAMENTO, CA 95826 USA PHONE: (800) 829-8106 FAX: (916) 428-1728 www.elevatorcontrols.com		JOB NUMBER:	16-18550
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FILE: J18550_6b.dwg		DATE:	08/23/16
		PAGE NUMBER:	6b



JOB NAME:			
438 W. 51ST ST SE1			
CUSTOMER:			
G-TECH ASSOCIATES, LLC			
ENGINEERED BY:		DATE:	
Jason Kirlis		10/27/16	
		REVISION DATE:	
		CONTROLLER MODEL:	
		PIXEL AC VECTOR-MRL-S	
6150 WAREHOUSE WAY SACRAMENTO CA 95828 USA PHONE: (800)828-8106 FAX: (916)428-1728 www.elevatorcontrols.com		JOB NUMBER:	
		16-18550	
M_PIXEL-7.dwg		CONTROLLER ID:	PAGE NUMBER:
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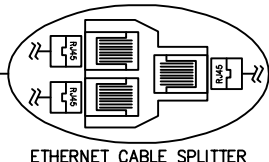
P-COP BOARD (FRONT) - FIXTURE INTERFACE			
JOB NAME:			
438 W. 51ST ST SE1			
CUSTOMER:			
G-TECH ASSOCIATES, LLC			
ENGINEERED BY:	DATE:	REVISION DATE:	
Jason Kirlis	10/27/16		
		CONTROLLER MODEL:	
		PIXEL AC VECTOR-MRL-S	
		JOB NUMBER:	
		16-18550	
6150 WAREHOUSE WAY SACRAMENTO CA 95824 USA PHONE: (800)829-8108 FAX: (916)428-1728 www.elevatorcontrols.com		CONTROLLER ID:	
M. FILE: 8-dwg PJL: 815550_8-dwg		PAGE NUMBER:	
10/23/16		SIMPLEX 8	

RJ45 TERMINATION		
PIN	WIRE	COLOR
1 (CAN1+)	WHITE/ORANGE	
2 (CAN1-)	ORANGE	
3 (V-)	WHITE/GREEN	
4 (N/C)	BLUE	
5 (N/C)	WHITE/BLUE	
6 (V-)	GREEN	
7 (V+)	WHITE/BROWN	
8 (V+)	BROWN	



PORT
FRONT
VIEW

STANDARD 568-B WIRING



ALL SERIAL HALL FIXTURES MUST BE RATED 24VDC/0.5A MAX. PEAK/0.2A MAX. CONTINUOUS.
ALL HALL CAN COMMUNICATION CABLES ARE CAT5e TERMINATED WITH RJ45 CONNECTOR AND WIRED TO 568-B STANDARDS

1. CONNECT THE HALL CALL FIXTURE TO THE P-HALL BOARD I/O AS SHOWN IN THE EXAMPLE ABOVE.
2. CONFIGURE THE P-HALL BOARD DIP SWITCH SETTINGS FOR THE CORRESPONDING HALL CALL FIXTURE (P-HALL BOARD CONFIGURATION REFERENCE TABLE IS LOCATED ON PAGE QR4b).
3. USE HALL CAN CABLES AND SPLITTERS TO INTERCONNECT THE P-HALL BOARDS AS SHOWN IN THE EXAMPLE ABOVE, THESE CABLES PROVIDE HALL CAN COMMUNICATION & POWER (24VDC/GND) TO EACH P-HALL BOARD.

P-HALL BOARD INTERCONNECTIONS			
JOB NAME:			
438 W. 51ST ST SE1			
CUSTOMER:			
G-TECH ASSOCIATES, LLC			
ENGINEERED BY:	DATE:	REVISION DATE:	
Jason Kirlis	10/27/16		
		CONTROLLER MODEL:	
6150 WAREHOUSE WAY SACRAMENTO, CA 95824 USA PHONE: (800)829-8106 FAX: (916)428-1728 www.elevatorcontrols.com		PIXEL AC VECTOR-MRL-S	
FILE: J18550_g.dwg		JOB NUMBER:	
		16-18550	
M_PIXEL - g.dwg	03/26/16	CONTROLLER ID:	PAGE NUMBER:
		SIMPLEX	9

[illegible]

PIXEL BOARD NAMES		
NAME:	BOARD DESCRIPTION:	EC PART #:
P-PDB	PIXEL POWER DISTRIBUTION BOARD	17-002-129
P-MP	PIXEL MAIN MICROPROCESSOR BOARD	17-002-123
P-MP-IO	PIXEL MAIN MICROPROCESSOR I/O BOARD	17-002-124
P-TOC	PIXEL TOP OF CAR MICROPROCESSOR BOARD	17-002-121
P-COP	PIXEL CAR OPERATING PANEL MICROPROCESSOR BOARD	17-002-119
P-HALL	PIXEL HALL NODE BOARD	17-002-114
P-TB-M	PIXEL TERMINAL BOARD MACHINE ROOM CONNECTIONS	17-002-137
P-TB-C	PIXEL TERMINAL BOARD CARTOP CONNECTIONS	17-002-138
P-TB-H	PIXEL TERMINAL BOARD HOISTWAY CONNECTIONS	17-002-139
P-CNEX	PIXEL EXPANSION I/O BOARD CAN BUS	17-002-116
P-MP-RDOOR	PIXEL P-MP REAR DOOR I/O EXTENDER BOARD	17-002-128
P-HNA	PIXEL HALL NETWORK ADAPTER BOARD	17-002-135

RELAY TYPES		
#:	MANUFACTURER PART #:	EC PART #:
1	RUS4S-CD-110 4PDT 110VDC	04-001-001
2	TRN/D-O 311 2PDT 110VAC/DC	-
3	C-H XTCE115G00A	12-020-051A
4	RU4S-CA-110 4PDT 120VAC	04-001-005
5	PM17DY-110 4PDT 110VDC	04-002-001
6	PRD-11DHO-1102PDT 110VDC	04-002-002
7	KUP-14D35-1103PDT 110VDC	04-001-002
8	KUP-14A35-1203PDT 120VAC	04-001-006
9	PM17AY120 4PDT 120VAC	-
10	DS2-M-DC48 2PDT 48VDC	-
11	DS2-ML-DC48 2PDT 48VDC(L)	-
12	DS2-M-DC12 2PDT 12VDC	-
13	DS2-ML-DC12 2PDT 12VDC(L)	04-001-009
14	KUP-14D15-24 3PDT 24VDC	04-001-016
15	PT-570-512 4PDT 12VAC	04-001-014
16	PRD-11AHO-120 2PDT 120VAC	04-002-003
17	PT-570-048 4PDT 48VDC	04-001-015
18	PT-570-024 4PDT 24VDC	04-001-003
19	RU4S-A24 4PDT 24VAC	04-001-017
20	REVERSE PHASE RELAY	-
21	EHDB220C-1L 600V 220A 120VAC COIL	12-008-006A
22	KUP-14A35-240 3PDT 240VAC	04-001-008
23	CNS-35-92 TIMER 2PDT	04-005-002
24	EC-100-C TIMER	-
25	V23049-B1012-A122 4P 110VDC	-
26	V23050-A1110-A533 6P 110VDC	04-006-002
27	G5V2 DC48 2PDT	04-001-011
28	CA7-16C-01-110D CONTACTOR	-
29	PT-570-512 4PDT 12VAC	04-001-014
30	CA7-16-01 120VDC COIL	12-020-023
31	CA8-09-01-120 120VAC COIL	12-020-031
32	K10P-11A15-120 120VAC COIL 10A@277VAC	04-001-020
33	PRD-11AHO-240 2PDT 240VAC	04-002-005
34	G5V2 DC12 2PDT	04-001-010
35	-	-
36	-	-

STANDARD **FGR (FORCE GUIDED)**

 - RELAY COIL -

 - NORMALLY OPEN CONTACT -

 - NORMALLY CLOSED CONTACT -

(NUMBER INDICATES POLE AND FIXED CONTACT)

— — — — — - EC INTERNAL CONTROLLER WIRING

— — — — — - PC BOARD TRACE

- - - - - - FIELD WIRING (BY CUSTOMER)

— — — — — - HARNESS (IDC) TERMINAL

— — — — — - SCREW TERMINAL PCB MOUNTED

— — — — — - PANEL MOUNT SCREW TERMINAL

 - HIGH POWER TERMINAL BLOCKS

 - MICROPROCESSOR OUTPUT

 - SAFETY MICROPROCESSOR OUTPUT

 - SAFETY F.P.G.A. OUTPUT

 - OUTPUT W/ REPLACEABLE TRANSISTOR

 - MICROPROCESSOR INPUT

 - SAFETY MICROPROCESSOR INPUT

 - SAFETY F.P.G.A. INPUT

 - FUSE (DOT INDICATES TOP OF FUSE)

 - RESISTOR

 - RESISTOR WITH ADJUSTABLE TAP
(DOT INDICATES TOP OR LEFT AS INSTALLED)

 - DIODE

 - ZENER DIODE

 - LED

 - AC RATED CAPACITOR

 - NON POLAR CAPACITOR

 - POLAR CAPACITOR

 - MOV (VOLTAGE TRANSIENT SUPPRESSOR)

 - DIODE BRIDGE

 - PC BOARD SLIDE JUMPER ON/OFF
OFF ON JUMPED POSITION

 - PC BOARD DIP SWITCH
(9 POSITION)
ON OFF POSITION
ON POSITION

 - GROUND (EARTH GROUND)

 - MECHANICAL OPERATED CAM SWITCH

 - VANE SWITCH

 - DRIVING MACHINE OPERATED SWITCH

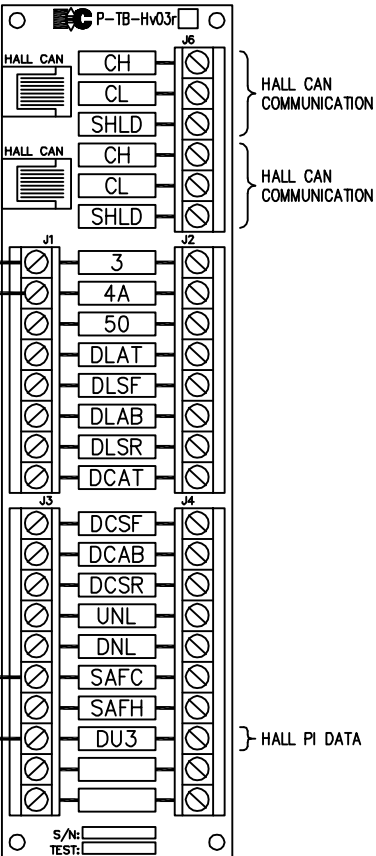
Diagram of a 36-pin connector pinout. The pins are arranged in a 6x6 grid. The top row is labeled 1, 2, 3. The right side is labeled OPEN, CLOSED, COIL, and COMMON. The diagram shows various internal connections between pins, including a central 3x3 grid of connections.

A schematic diagram of a 4-position selector switch. The switch is shown in a cross-sectional view with four distinct positions. The positions are labeled on the right side: 'CLOSE' at the top, 'OPEN' below it, 'COIL' below that, and 'COMM' at the bottom. The switch mechanism includes a central rotating shaft with a handle at the top. The handle has four detents corresponding to the four positions. The switch is housed in a rectangular frame with mounting screws at the corners. The internal contacts are visible for each position.

JOB NAME:		438 W. 51ST ST SE1	
CUSTOMER:			
G-TECH ASSOCIATES, LLC			
ENGINEERED BY:	DATE:	REVISION DATE:	
Jason Kirlis	10/27/16		
 ELEVATOR CONTROLS		CONTROLLER MODEL:	
		PIX AC VECTOR-MRL-S	
		JOB NUMBER:	
		16-18550	
6150 WAREHOUSE WAY SACRAMENTO, CA 95823-1054 PHONE: (800) 829-8106 FAX: (916) 428-1728 www.elevatorcontrols.com			
M_PIXEL -10.dwg	10/05/16	PACKAGE NUMBER:	
FILE: jh550_10.dwg	SIMPLEX 10		

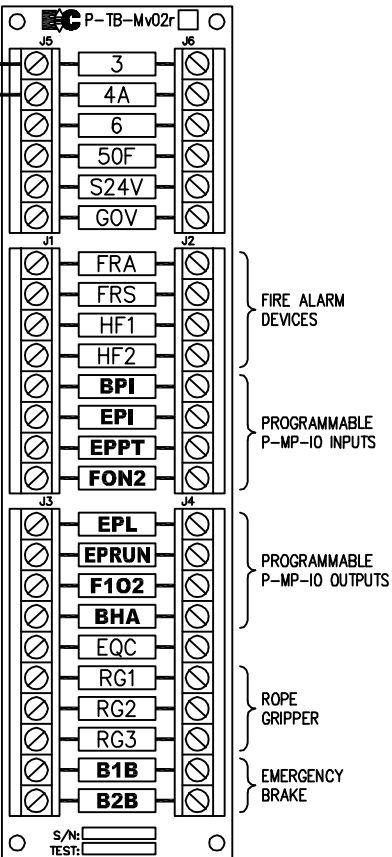
HOISTWAY TERMINALS

(1) 17-002-139v03 PIXEL TERMINAL BLOCK BOARD - HOISTWAY (P-TB-H)



MACHINE ROOM TERMINALS

(1) 17-002-137v02 PIXEL TERMINAL BLOCK BOARD - MACHINE ROOM (P-TB-M)
(4) 10-203-005 BEIGE PANEL MOUNT TERMINAL BLOCKS



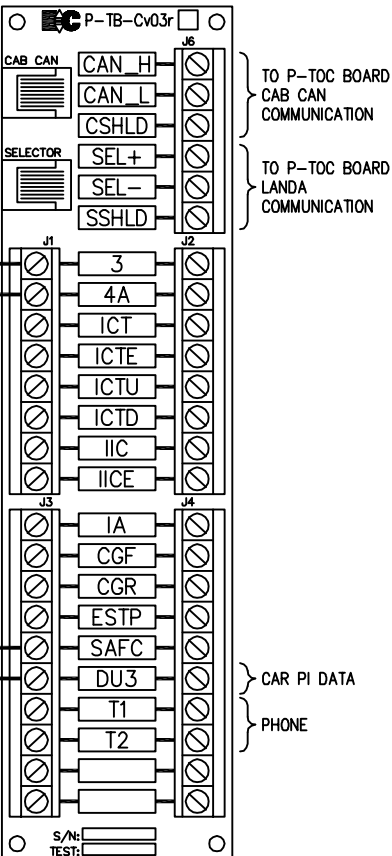
PANEL MOUNT TERMINALS
BELOW P-TB-M BOARD

B1			B1	
B2			B2	
EPTC			EPTC	
GVT			GVT	

MAIN BRAKE
SHUTDOWN
GOVERNOR SHEAVE TENSION

CARTOP TERMINALS FOR TRAVELER CABLE

(1) 17-002-138v03 PIXEL TERMINAL BLOCK BOARD - CARTOP (P-TB-C)
(13) 10-203-005 BEIGE PANEL MOUNT TERMINAL BLOCKS



PANEL MOUNT TERMINALS
BELOW P-TB-C BOARD

TOC1			TOC1	
TOC2			TOC2	
WHT			WHT	
BLK			BLK	
GRN			GRN	
BPIX			BPIX	
21A			21A	
21B			21B	
21C			21C	
21D			21D	
22			22	
22A			22A	

TOC POWER
CAB POWER (115VAC)

RESISTOR BOX TERMINALS IN REMOTE CABINET

(15) 10-203-005 BEIGE PANEL MOUNT TERMINAL BLOCKS
(3) 10-201-012 POWER TERMINAL BLOCK 600V 175A 2 POLE

RBP1			RBP1	
RBP2			RBP2	
RB1A			RB1A	
RB1B			RB1B	
RBA			RBA	
RBB			RBB	
R7			R7	
R8			R8	
R3A			R3A	
EBH			EBH	
R4A			R4A	
R5A			R5A	
R6A			R6A	
FN1			FN1	
FN2			FN2	

DB1
DB2
DB3
DB4
DB5
DB6

RESISTOR BOX TERMINALS IN MAIN CONTROLLER

(15) 10-203-005 BEIGE PANEL MOUNT TERMINAL BLOCKS
(3) 10-201-012 POWER TERMINAL BLOCK 600V 175A 2 POLE

RBP1			RBP1	
RBP2			RBP2	
RB1A			RB1A	
RB1B			RB1B	
RBA			RBA	
RBB			RBB	
R7			R7	
R8			R8	
R3A			R3A	
EBH			EBH	
R4A			R4A	
R5A			R5A	
R6A			R6A	
FN1			FN1	
FN2			FN2	

DB1
DB2
DB3
DB4
DB5
DB6

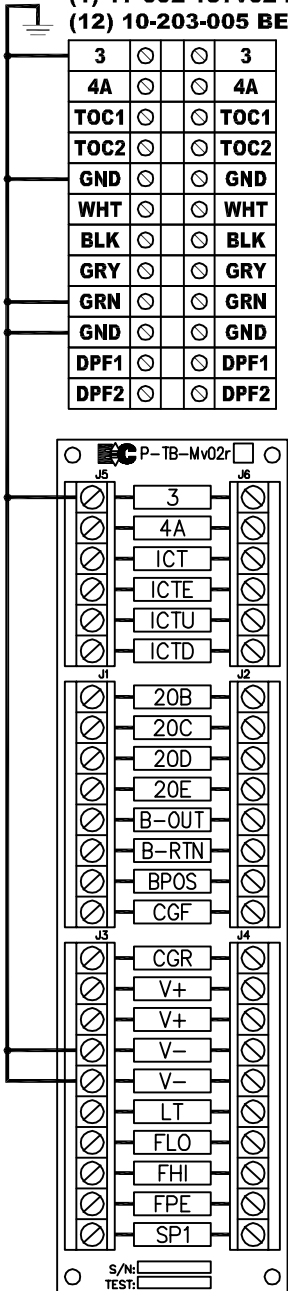
TERMINALS IN MAIN CONTROLLER

(0) 10-203-005 BEIGE PANEL MOUNT TERMINAL BLOCKS

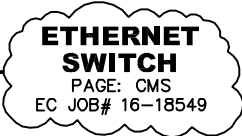
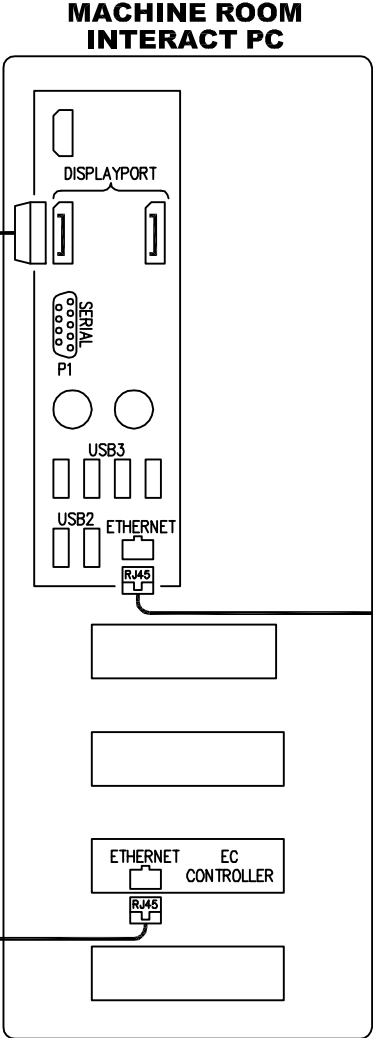
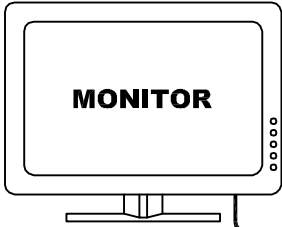
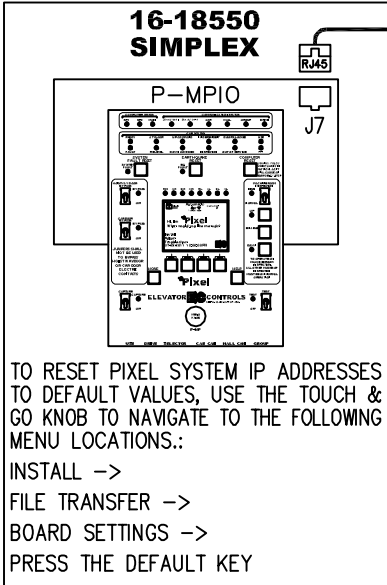
TOC (TOP OF CAR) BOX TERMINALS

(1) 17-002-137v02 PIXEL TERMINAL BLOCK BOARD (P-TB-M)
(12) 10-203-005 BEIGE PANEL MOUNT TERMINAL BLOCKS

3			3	
4A			4A	
TOC1			TOC1	
TOC2			TOC2	
GND			GND	
WHT			WHT	
BLK			BLK	
GRY			GRY	
GRN			GRN	
GND			GND	
DPF1			DPF1	
DPF2			DPF2	



PIXEL CONTROLLER TERMINAL LABELS & ORDER			
JOB NAME:			
438 W. 51ST ST SE3			
CUSTOMER:			
G-TECH ASSOCIATES, LLC			
ENGINEERED BY:	DATE:	REVISION DATE:	
Jason Kirlis	10/27/16		
ELEVATOR CONTROLS		CONTROLLER MODEL:	
6150 WAREHOUSE WAY SACRAMENTO, CA 95826 USA PHONE: (800) 829-8108 FAX: (916) 428-1728 www.elevatorcontrols.com		PIXEL AC VECTOR-MRL-S	
M_PIXEL-TS.dwg		JOB NUMBER:	
FILE: J18550_TS.dwg		16-18550	
		CONTROLLER ID:	
		SIMPLEX	
		PAGE NUMBER:	
		TS	



CAT5E CABLE
150 FEET

EC CONTROLLER PORT NETWORK CARD FACTORY SETTINGS	
IPV4 ADDRESS:	10.10.1.40
SUBNET MASK:	255.255.255.0

MACHINE ROOM INTERACT PC ETHERNET PORT FACTORY SETTINGS	
IP ADDRESS:	192.168.1.102
SUBNET MASK:	255.255.255.0

INTERACT MONITORING SYSTEM PARTS LIST:		
QUANTITY	EC PART #	PART DESCRIPTION
2	25-002-017	INTERACT PC (1 SERIAL PORT, KEYBOARD & MOUSE)
	25-002-0XX	INTERACT LAPTOP PC
2	25-002-018	LCD MONITOR DISPLAY (20")
	25-002-0XX	LCD MONITOR DISPLAY (22")
	25-002-005	ULTRA SLIM KEYBOARD (USED WITH THE G900 CABINET)
	25-002-0XX	PRINTER INK JET
	19-001-023-14ft	ETHERNET CABLE CAT5e 14 FEET
1	19-001-023-X	ETHERNET CABLE CAT5e 150 FEET
1	25-002-022	32-BIT 10/100/1000MBPS GIGABIT PCI ADAPTER
	25-002-023	32-BIT 10/100/1000MBPS GIGABIT PCIe ADAPTER
	25-002-024	USB 3.0 TO GIGABIT ETHERNET NETWORK ADAPTER
	25-002-025	8 Port 10/100Mbps Fast Ethernet Switch

INTERACT MONITORING SYSTEM INSTALLATION			
JOB NAME:			
438 W. 51ST ST SE1			
CUSTOMER:			
G-TECH ASSOCIATES, LLC			
ENGINEERED BY:	DATE:	REVISION DATE:	
Jason Kirlis	10/27/16		
 ELEVATOR CONTROLS 6150 WAREHOUSE WAY SACRAMENTO, CA 95828 USA PHONE: (800)829-8106 FAX: (916)428-1728 www.elevatorcontrols.com		CONTROLLER MODEL:	
		PIXEL AC VECTOR-MRL-S	
		JOB NUMBER:	
M_PIXEL-IMS.dwg		16-18550	
FILE: J18550_IMS.dwg		10/04/16	
		CONTROLLER ID:	PAGE NUMBER:
		SIMPLEX	IMS